

Rough-Wall Boundary Layers

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FLOW-NORDITA Spring School on TURBULENT BOUNDARY LAYERS

KTH Royal Institute of Technology Stockholm, Sweden April 6-9, 2010

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Outline



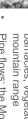
- Historical perspective and current motivation
- 2 Fundamentals: the log law as a 'map' – self-similarity
- ယ Definition of scales, distinction between internal flows (pipes, channels) and external flows (boundary layers) - what are the differences?
- 4 Roughness definition – why this is complicated
- 5 The Moody chart for pipe flow
- 6. Townsend "outer similarity"
- 7. Boundary layer roughness: the atmospheric surface layer
- ∞ Effects of very large roughness – limits to classical definitions
- 9 Outlook: what are the outstanding issues??

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History and motivation





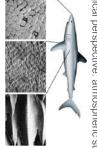




per annum, but ocean shipping uses 2.1 M barrels

















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Fundamentals



- Contrasting types of roughness: importance of the roughness distribution
- The log law as a 'map' self-similarity
- Coles' profile: changes to accommodate roughness -Hama's roughness function
- Hydraulically smooth, transitional and full roughness
- Meteorological definitions

Definitions

- Historically, definitions arise from early work
- Fully developed flow very useful because surface friction simply related to pressure drop
- Define coefficient of resistance, λ : $\tau_{\scriptscriptstyle w} = \frac{1}{8} \lambda \rho \overline{U}^2$
- Define friction factor, $f: \tau_w = \frac{1}{2} f \rho \overline{U}^2$
- Compare with skin-friction coefficient (external geometries) $C_f = \frac{\tau_w}{\frac{1}{2}\rho U_e^2}$
- Use h (channel half-height), pipe radius R and boundary layer thickness δ interchangeably;

similarly U_{cl} and U_e

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ے و	$\overline{U} = \int U$	h
,	\mathcal{G}	

$-\frac{h}{2}\frac{dp}{dx}$	Square- sectioned duct, 2hx2h
$-h\frac{dp}{dx}$	2D duct, height 2 <i>h</i>
$-\frac{R}{2}\frac{dp}{dx}$	Pipe
$ au_w$	

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Basic properties



- $\lambda = 8 \left(\frac{u_r}{\overline{U}} \right)^{-} = 4 \left(\frac{U_{cl}}{\overline{U}} \right)^{-} C_f = 4 f$
- Fluid response depends on a large number of parameters

$$\frac{U}{u_{\tau}} = f(y^+, k^+, h^+, \text{ geometrical properties})$$

- The "roughness sublayer", $y \le 10k$: can we expect roughness effects to be confined within it?
- with velocity is quadratic roughness is large, form drag dominates and wall shear-stress variation pressure drop across a particular element goes as k^2 , that is, when Larger roughness elements exert a disproportionately large effect -
- "Shielding" of smaller roughness elements by larger ones
- Hence, for the sake of argument, identify k as the maximum roughness <u>height</u> in a distribution.

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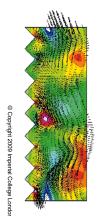
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A physical description



- Friction drag increases once wall is no longer hydro-dynamically smooth
- For "small" roughness, the effects may be scaled by the increase in wallfriction velocity, $u_{\tau} = \sqrt{\tau_w/\rho}$ alone.
- The viscous sublayer is replaced by the roughness sublayer, $y \le 10k$
- Near the roughness elements, there is an increase in dissipation (over that for an equivalent smooth surface) which is not matched by an increase in production
- Riblets impede near-wall cycle of energy production but without increase in form drag of roughness elements





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A physical description - inner-outer interaction



- If the direct effects of roughness do not extend beyond the roughness sublayer (no interaction), the "local equilibrium" approximation ("production = dissipation") can be expected to hold
- inner (k) outer (R) scale separation is not possible and the lol can be interaction (IoI): for large roughness, $k/R \to 1$ and even when $k^+ \sim R^+ \to \infty$ Roughness may be viewed as a form of "bottom-up" inner-outer expected to be large.
- A high-Reynolds-number effect may be interpreted as a "top-down" interaction:



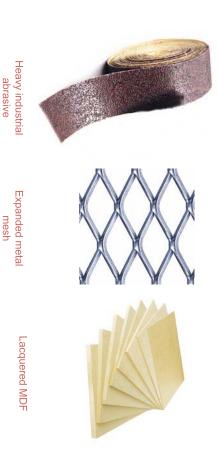
Scorer (Hunt & Morrison 2000)

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Types of roughness



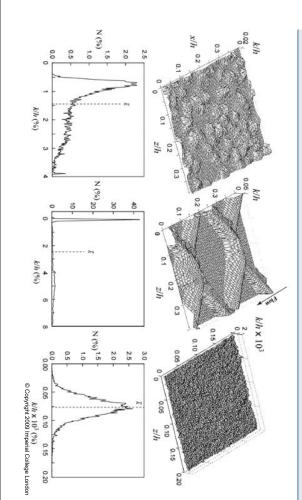


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Roughness definition: laser profilometer





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Similarity



The near-wall mean velocity profile depends on:

$$U = f_i(\tau_w, \rho, \nu, y, k, \text{ roughness properties})$$

$$\frac{U}{u_{\tau}} \cong f_i(y^+, k^+)$$

In the outer layer, for the velocity deficit we have:

$$U_{cl} - U = f_o(\tau_w, \rho, y, h)$$

$$U_{cl} - U = f_o(\frac{y}{I}, \frac{u_t}{I}, \beta) \cong f_o(\frac{y}{I}, \frac{u_t}{I}, \beta)$$

$$\frac{U_{cl} - U}{u_{t}} = f_{o} \left(\frac{y}{h}, \frac{u_{t}}{U_{cl}}, \beta \right) \cong f_{o} \left(\frac{y}{h} \right)$$

The shear stresses will behave in a similar fashion - hence

$$-\frac{\overline{uv}}{u_t^2} = g_i(y^+, k^+) \quad \text{and} \quad -\frac{\overline{uv}}{u_t^2} \cong g_i(\frac{y}{h}, \frac{u_t}{U_{cl}}, \beta)$$

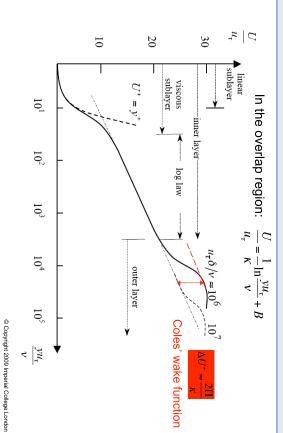
Note that in the outer layer, both the velocity deficit and the stresses are taken to be independent of the surface roughness - "Townsend outer-layer similarity" thus the affect of the roughness appears through an increase in skin friction

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Self-similarity: the log law on a smooth surface





Complete or self-similarity



- a single velocity scale, $u_{\rm r}$ and a single length scale, $y_{\rm r}$ and κ can be taken to be a universal constant The log law is self-similar: this means that it is specified completely by
- Self-similarity implies that the constant in the log argument may be freely chosen - a consequence of simultaneous overlap
- Therefore as rong we written for outer variables $U_{cl}^{+}-U^{+}=-\frac{1}{\kappa}\ln\left(\frac{y}{h}\right)+B^{*}$ Therefore as long as there is a sufficient separation of scales, the log

$$U_{cl}^{+} - U^{+} = -\frac{1}{\kappa} \ln \left(\frac{y}{h} \right) + B^{*}$$

By extension, it may also be written for a rough surface in the form

$$U^{+} = \frac{1}{\kappa} \ln \left(\frac{y}{k} \right) + B_2$$

A sufficient separation of scales $\frac{V}{U_\tau} << k << h$ also implies that both B^* and $B_2 \to {\rm constants}$ B^* and $B_2 \rightarrow$ constants

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Describing roughness effects



Reynolds number is 'high' - so assume log law is valid $\frac{1}{d}$

$$\frac{U}{u_{\tau}} = \frac{1}{\kappa} \ln \frac{(y-d)u_{\tau}}{v} + B - \frac{\Delta U_R}{u_{\tau}}$$



- d ($\langle k \rangle$) is zero-plane displacement, representing height at which momentum is extracted
- $\Delta U_{R}^{+} = \frac{\Delta U_{R}}{L}$ is the velocity shift relative to the log law for a smooth surface - the Hama roughness function For a smooth surface, expect d and $\Delta U_R^+ \rightarrow 0$: "hydraulically smooth"
- But how do they change with k?

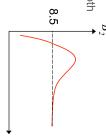
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Transitionally rough and fully rough



- For $k^+ < 5$, expect surface to be hydraulically smooth \uparrow
- For convenience, drop d and write

$$\begin{split} \frac{U}{u_r} &= \frac{1}{\kappa} \ln \frac{yu_r}{v} + B_1(k^+) \\ &= \frac{1}{\kappa} \ln \frac{y}{k} + B_2(k^+) \end{split}$$



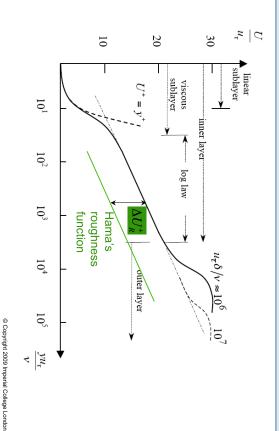
- B_I and B_2 are roughness functions: B_2 more useful because, as k^+ number effects absorbed into a single term increases, log law requires scale separation $y>>k\,$ and Reynolds
- Hence for $k^+ > \sim 70$, $B_2 \rightarrow 8.5$: "fully rough"
- and for 5 \sim < k^+ \sim < 70, $B_2 \rightarrow f(k^+)$: "transitionally rough"

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The log law - fully rough surface





For a fully rough surface...



- Meteorological definitions of the log law $U^+ = \frac{1}{\kappa} \ln \left(\frac{y d}{y_0} \right)$
- Where y_0 is the roughness length (of the order 0.1k) and is geometry-specific
- The velocity shift may be written: $\Delta U_R^+ = \frac{1}{\kappa} \ln(k^+) + B + \frac{1}{\kappa} \ln(\frac{y_0}{k})$
- In what follows, it will be important to distinguish Hama's roughness function ΔU_R^* from Coles' wake function $\Delta U^* = \frac{211}{K}$

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3. Pipe flow



- . Prandtl's universal law for friction in smooth pipes
- 2. Nikuradse's sand-grain roughness
- 3. Colebrook's roughness function
- The Moody chart
- 5. Recent developments
- . Roughness characterisation

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Prandtl and Nikuradse



In smooth pipes, a friction factor relationship may be obtained by assuming self- (complete) similarity of the mean velocity profile and integrating the log law:

$$\frac{1}{\sqrt{\lambda}} = 2.0\log(\text{Re}\sqrt{\lambda}) - 0.8$$

- · This is Prandtl's universal law of friction for smooth pipes
- It has recently been revised (McKeon et al. 2005) for $31x10^4 \le \text{Re}_D \le 18x10^6$
- Prandtl's law may be expressed as $\frac{1}{\sqrt{\lambda}} = 2\log\left(\frac{\operatorname{Re}\sqrt{\lambda}}{2.51}\right)$
- In the fully-rough regime, Nikuradse showed that

$$\frac{1}{\sqrt{\lambda}} = 2\log\left(\frac{3.71D}{k_s}\right)$$

i.e. the friction factor is determined fully by the relative roughness. Nikuradse used sand-grain roughness, of height $k_{\!\scriptscriptstyle S}$

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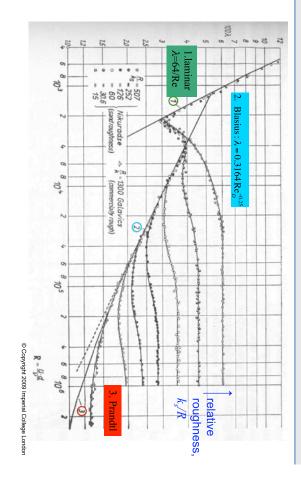
Sand-grain roughness

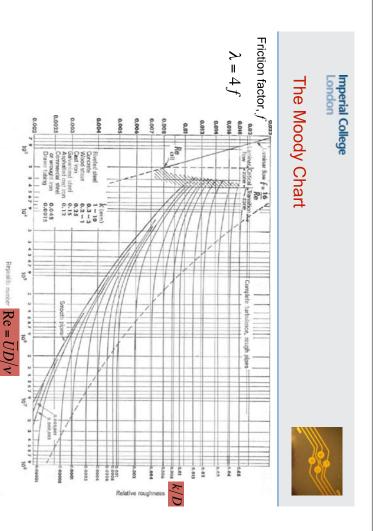


- In a famous set of experiments, Nikuradse measured the pressure drop in a rough-walled pipe using close-packed sand of uniform size so-called "sand-grain roughness", $k_{_{\! S}}$
- These data can be used to define an "equivalent sand-grain roughness" by comparing the friction factor for a surface of arbitrary roughness (in the fully-rough regime) to that for Nikuradse's sand-grain roughness
- Unfortunately, sand-grain roughness is of a specialised form "monodisperse" and close-packed: naturally occurring roughness is "polydisperse" (a wide distribution) with spaces
- "Nikuradse's fully-rough results on the same unrealistic uniform-sand surface simply define a useful common currency roughness size like paper money, valueless in itself but normally acceptable as a medium of exchange" (Bradshaw 2000).

Nikuradse's results for sand-grain roughness







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The Colebrook roughness function



Colebrook also devised a "transitional" roughness function by

$$\frac{1}{\sqrt{\lambda}} = -2\log\left(\frac{k_s}{3.71D} + \frac{2.51}{\text{Re}\sqrt{\lambda}}\right)$$

- At small relative roughness, k_s/D , it asymptotes to Prandtl's law. Similarly the function represents the fully-rough regime as $Re \Rightarrow \infty$.
- and fully rough functions) taking the harmonic mean of the separate log arguments for smooth However, there is little theoretical justification for its form (equivalent to
- Colebrook also rewrote the function in the form

$$2\log\left(\frac{3.71D}{k_s}\right) - \frac{1}{\sqrt{\lambda}} = 2\log\left(\frac{3.29}{k_s^+} + 1\right)$$

This makes the choice of independent variable clearer, but...

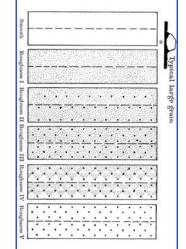
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Major Colebrook



- Colebrook & White (1937) which were much more different types of roughness measured λ for five and Colebrook (1939) representative.
- In particular, very large Hence "shielding" of the roughness grains were used on only about 2% of the area
- small grains by the larger





Colebrook roughness details



	Description of surface	λ (fully rough)	k_s mm
.l	Uniform sand 0.35 mm diam. $(=k)$ in 2 inch pipe	0.0369	
	Uniform sand with large 3.5 mm grains on 2.5% area	0.0425	
	Uniform sand with large 3.5 mm grains on 5% area	0.047	
₹	48% area smooth, 47% area uniformly covered with fine grains, 5% area large grains	0.041	
<	95% area smooth, 5% area large grains	0.034	

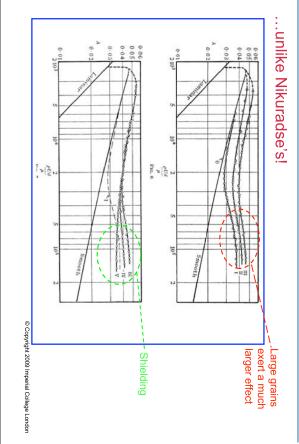
Equivalent sand-grain roughness $\lambda = \left[2\log\frac{3.71}{k_s}\right]^{-2}$

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Colebrook's data are not inflexional...



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Colebrook's roughness function



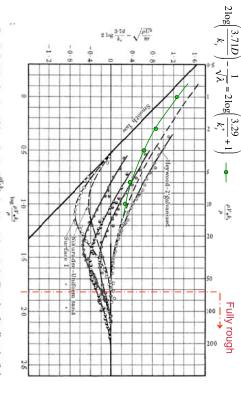


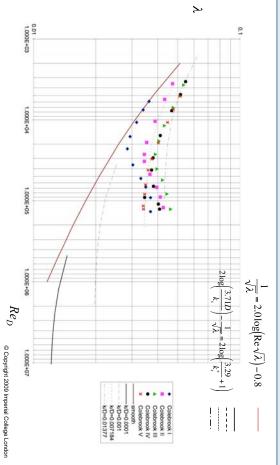
Fig. 10—Deviations from "rough" law as function of \(\frac{\rho^2 \cho_2 \cho}{\rho}\), where \(\rho_1\) is equivalent grain size. The surfaces I to V are described in fig. 6 and in Table I. O surface II; O surface II; O surface III; O surface IV; O surface V.

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Moody chart with Colebrook's data



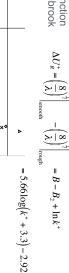


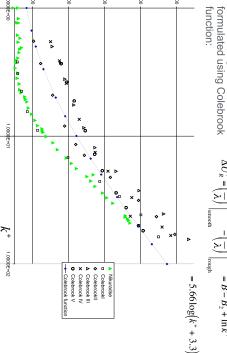


Hama's roughness function for Colebrook's data



 $\Delta U_{\scriptscriptstyle R}^{\scriptscriptstyle +}$



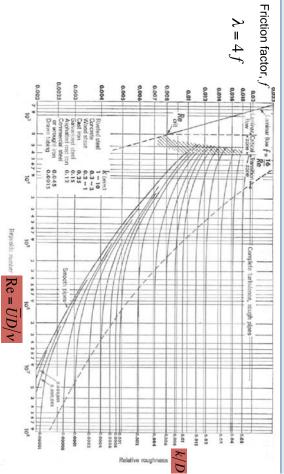


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The Moody Chart



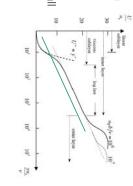


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Difficulties with the Colebrook function



- Colebrook's transitional roughness function does not follow his own data
- relative roughness function, $\Delta U_{\rm R}^+$, which avoids ill-conditioned behaviour of the roughness function at small plotting the data as Hama's roughness These differences are also clear when
- the sublayer by extrapolation of the log law $\Delta U_{\scriptscriptstyle R}^{\scriptscriptstyle +}$ is also a good measure of changes to
- somewhat simplistic and rests primarily on fully roughness function arguments taking the harmonic mean of the smooth and The analysis for its part-justification is



serving in the British Army since 1939, was unable to submit a his chart. discussion". Lewis Moody (1944) in discussion of the paper presenting "It is regretted that Professor (now Major) Colebrook, who has been

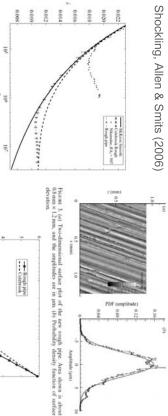
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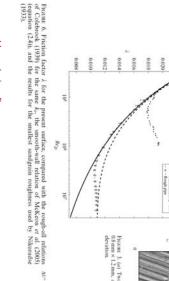
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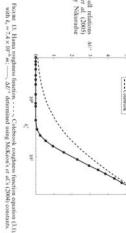








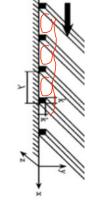
k/D=1/17,000, Gaussian

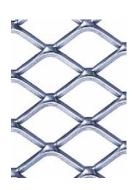


Roughness characterisation



- Difficulties with Moody chart stem from the Colebrook transitional roughness function
- subsumed into a fully-rough equivalent effects of a distribution of roughness sizes Equivalent sand-grain roughness not very absorbed into a single variable, k_s , and sizes, orientation, spacing, shielding are all useful – effects of a distribution of roughness
- So far we have focused on so-called *k*-type
- 2D spanwise ribs *d*-type roughness shows atypical behaviour
- different to "3D" roughness We consider a "2.5D" mesh later - very





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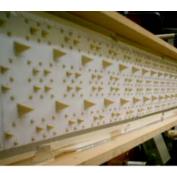
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Roughness characterisation



- Fractals? A single dimension that provides a true measure of surface topology
- Non-integer fractal dimension, $N = \frac{\log N(I)}{2}$
- Or use Euclidean (integer) dimension and exploit similarity, so lengthscale = $\sqrt{\text{area}}$ or $\sqrt[3]{\text{vol}}$
- But still have to contend with variable Re_k for standing vortex pair (≈ 25) or 'shedding' (≈ 50)





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Effects of very large roughness

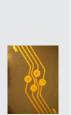


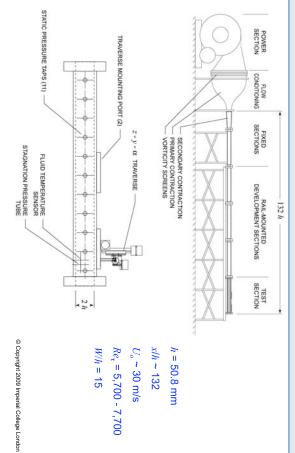
- Do the details of the roughness leave their imprint on the
- Does self-similarity of the mean velocity profile persist?
- Does Townsend outer-layer similarity persist?
- rough and smooth surfaces? What aspects of turbulence structure are common to both
- be expected"... • Jiménez suggests that k/h < 2.5% "before similarity laws can
- If so, is this limit dependent on other roughness details?
- Is it the same for both internal and external flows?
- So what happens for k/h > 4%?
- Townsend outer-layer similarity It is likely that self-similarity is a stronger requirement than

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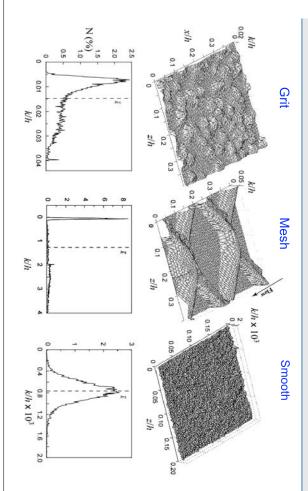
Channel flow facility





Surface topologies





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Grit and mesh roughness



- Grit peak-to-peak $k_{max} \approx 1.8$ mm, k/h = 3.5%
- Isotropic
- Non-Gaussian, positively skewed
- Mesh
- $k_{max} \approx 4.0 \text{ mm}, k/h = 7.9\%$
- Anisotropic
- $L_z/L_x = 2.6$, $L_z/k_{max} = 7.5$, $L_x/k_{max} = 2.9$ "2.5D"
- Single-wire results $\ell^+ \approx 40 60$

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Experimental parameters



Smooth	Mesh	Mesh	Mesh	Grit	Grit	Grit	Surface
41.9	25.0	23.2	21.1	28.6	26.7	24.7	$u_{c'}$
31.5	20.5	18.8	17.3	24.4	22.8	21.0	<u>u</u>
4480	6270	5830	5230	5540	5130	4780	$Re_{ au}$
12.4	7.38	6.77	6.12	8.43	7.78	7.28	Re _h x 10 ⁻⁴
ı	493	458	410	216	200	186	(k)u/v

$$Re_{\tau} = \frac{u_{\tau}h}{v}$$

$$\operatorname{Re}_h = \frac{U_{cl}h}{v}$$

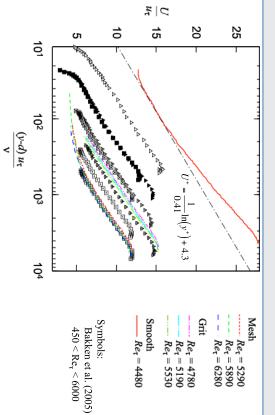
$$\overline{U} = \frac{1}{h} \int_{0}^{h} U(y) dy$$

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Mean velocity: viscous scaling





Mean velocity: inner scaling

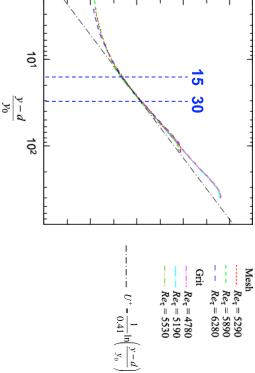


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Outer scaling - detail

16





 $\frac{U_{cl}-U}{u_{\tau}}$ 8

12

smooth

 $\frac{1}{2}$

œ

0

12

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10-2

10-1

100

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→collapse $y/h > \sim 0.3$

Symbols:

Bakken *et al.* (2005) $450 < \text{Re}_{\text{t}} < 6000$

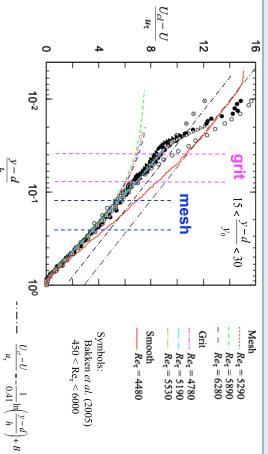
 $\frac{U_{cl} - U}{u_{\tau}} = -\frac{1}{0.41} \ln \left(\frac{y - d}{h} \right) + B$

 $\frac{y-d}{h}$

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Mean velocity: outer scaling





 $\frac{y-d}{h}$

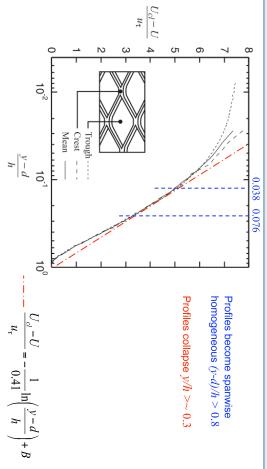
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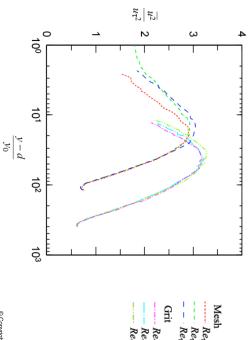
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Mean velocity: outer scaling - mesh detail





Second moment: inner scaling



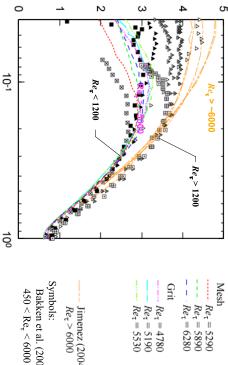


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Second moment: outer scaling





 $\frac{u^2}{u^2}$



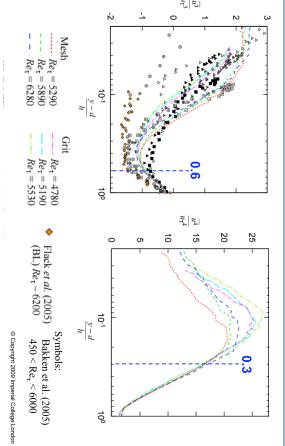
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 $\frac{y-d}{h}$

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Higher-order moments: outer scaling





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- Very-rough channel flow: summary
- similarity, that on '2.5D' mesh ($k/h \approx 8\%$) does not

While mean velocity profile on isotropic grit ($k/h \approx 4\%$) shows self-

- at which mean velocity profiles become spanwise-homogeneous Coles' wake parameter, "wake strength", $\Delta U^{+} = 2\Pi/\kappa$ decreases with The lack of self-similarity on the mesh surface extends above the point
- Note however, that II may only be defined once the log law is increasing roughness (smooth: 3.2; grit: 0.82; mesh 0.61) established
- All u-component moments scale with outer variables Townsend outer-layer scaling: y/h at which this begins varies with order of
- even if $\frac{1}{\rho} \frac{\partial p}{\partial y} = \frac{\overline{\partial v^2}}{\partial y}$: therefore it is perhaps unsurprising that scaling with u_τ is robust

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5. Boundary layers: differences & similarities



- Does mean velocity profile show self-similarity?
- Is wake parameter independent of surface roughness, these effects being represented by ΔU_{R}^{+} alone (Tani 1987)?
- Do boundary layers show Townsend's outer-layer similarity?
- Are there differences in structure?

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Self-similarity of mean velocity



- Typically, u_c is estimated using Preston tube, by assuming a "constant stress" layer, $-uv = u_c^2$ or by a Clauser chart: more measurements are required using a drag balance
- It is clearly not possible in the atmospheric surface layer to perform a rigorous check of simultaneous overlap to determine extent of self-similarity

y-d

- Flack *et al.* (2007), Connelly *et al.* (2006), Castro (2007) all demonstrate collapse of velocity defect profiles in outer layer for $k/\delta \le 20\%$
- But Krogstad et al. (1992) and Keirsbulck et al. (2002) show that wake strength increases on rough walls - is this inconsistent?
- Flack *et al.* (2007) also show that, as k/δ increases, the growth rate of the boundary layer increases i.e. boundary layer 'rides' over the roughness

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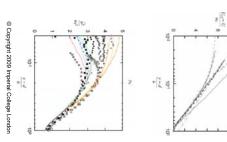
Townsend outer-layer similarity



- Townsend (1956, 1976): Outside of the sublayer, flow scales with u_{τ} only
- Roughness does not affect u_r scaling in either pipes or boundary layers (e.g. Shockling et al. 2006 Schultz & Flack 2007, Flack et al. 2005)
- Outer-layer similarity holds even for very-rough-wal Boundary-layers (Flack et al. 2007, Castro 2007)
- Roughness geometry does not affect u_{ϵ} scaling in a ribbed channel (Krogstad *et al.* 2005)
- Open question: Krogstad et al. (1992) suggested that outer layer is affected by roughness: differences in wake strength and shear stresses These results not yet reproduced but there may be

boundary layer flows

fundamental differences between channel and

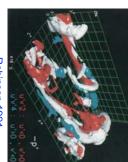




Near-wall structure



- Near-wall cycle changes obviously
- Roughness improves isotropy near wall: \overline{u}^2 depressed but v^2 increases
- Increased frequency and magnitude of sweep and ejection events
- May be related to an increase in hairpin inclinations in boundary layers relative to smooth-wall (Krogstad *et al.* 1992, Krogstad & Antonia 1994, Bakken *et al.* 2005)

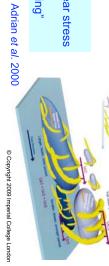


Robinson 1991



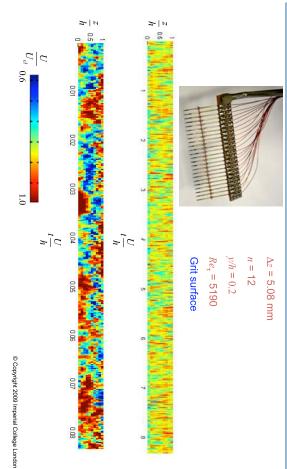
Large structures

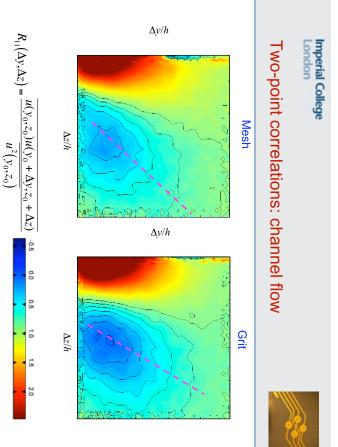
- 2007) have also been identified In smooth-wall boundary layers, "superstructures" (Hutchins & Marusic identified (Kim & Adrian 1999) In smooth pipe flow, "Very-Large Scale Modules" (VLSMs) clearly
- shear-stress and energy These are dynamically significant: typically they carry about half the
- In rough-wall boundary layers:
- Wu & Christensen (2007) suggest "similarity of spatial structure" but using autocorrelations
- Volino et al. (2007) suggest that "hairpin packets area prominent feature and much the same as its smooth-wall counterpart"
- packets carry roughly half the turbulence kinetic energy and shear stress
- fill most of the boundary layer
- at least 20δ in length "meandering"

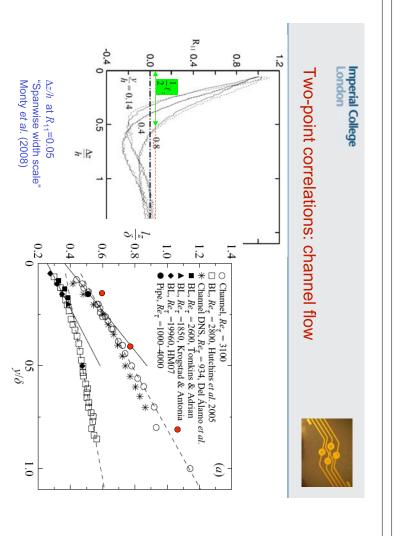


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Imperial College Large structures: time histories - channel flow



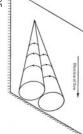




Large structures: summary



- VLSMs appear on both rough and smooth surfaces
- In two-point correlations these appear as Townsend's "backflow" region
- therefore relating to strain rate rather than viscous shear plane result from non-normality - essentially not a viscous process and Likely that large structures elongated in x and with circulation in (y,z)-
- extent for outer-layer similarity Townsend's "attached wall eddies" - probably responsible to a large



- Differences in detail: on rough surfaces, l_z is larger
- Spatial correlation on a rough surface is essential vigorous "jitter rather than "meandering"

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Outlook



- Definition of surface topology in a useful way is a key challenge
- The Moody chart offers some further challenges in the "transitional"
- required in experiments using large relative roughness In order to identify real differences between channel and boundary layer flows, accurate, independent and direct estimates of u_{τ} are
- It has been suggested that the effect of roughness on wake strength is unravelled without an unambiguous definition of the log law not the same for channel and boundary layer flows: this cannot be
- Self-similarity requires a demonstration of simultaneous overlap
- The extent of Townsend outer-layer similarity has yet to be fully
- irrespective of the surface condition Large streamwise vortices appear to be a dominant feature

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