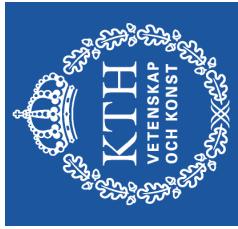


Hydrodynamic stability 2004

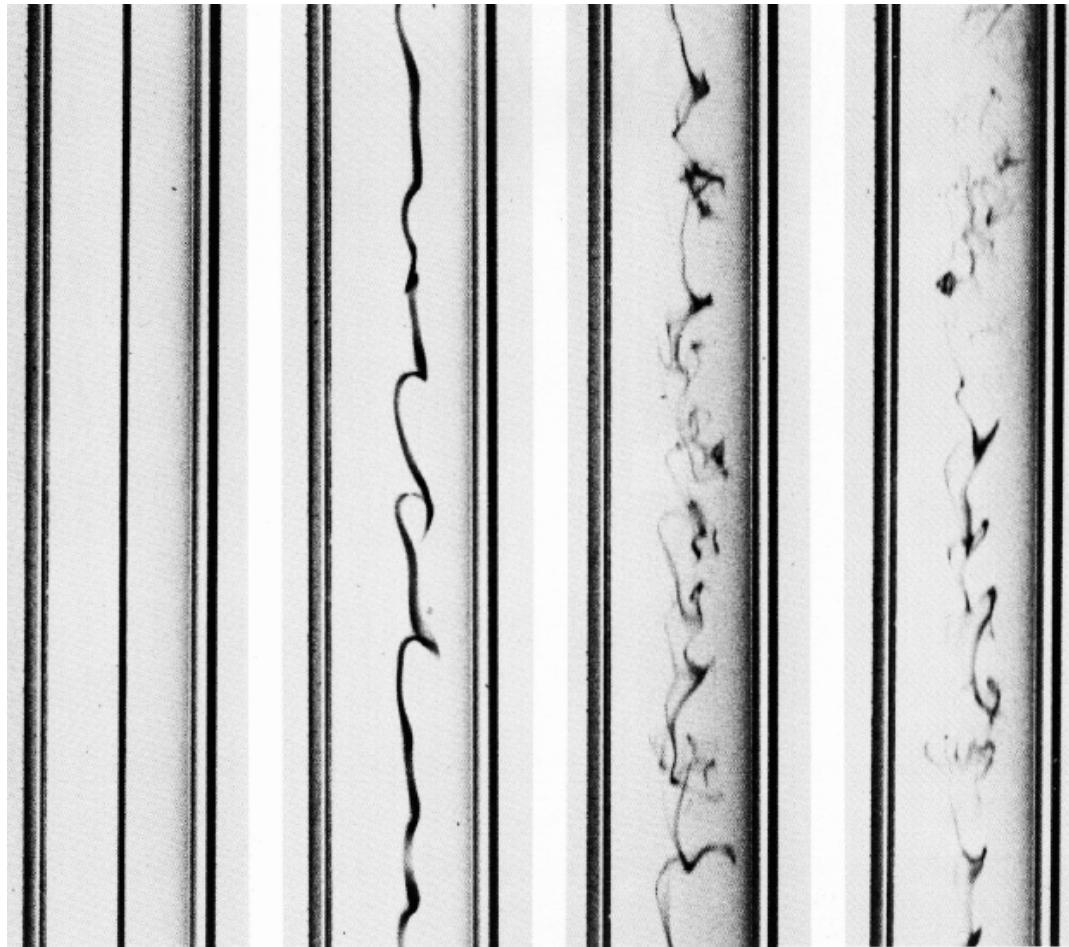
- Part of graduate student course,
Department of Mechanics
- Lectures: 16/9 8-12, K52
30/9 8-12, L44
6/10 8-12, K51
- Projects: 10/11 8-12, K52
17/11 8-12, E36
- Book: **Stability and Transition in Shear Flows**
Peter J. Schmid
Dan S. Henningson
Applied Mathematical Sciences 142
- Further info on web
www2.mech.kth.se/~henning



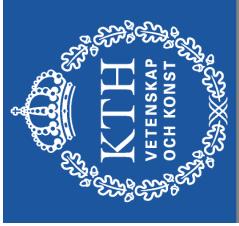
Course on Stability and Transition



Reynolds pipe flow experiment

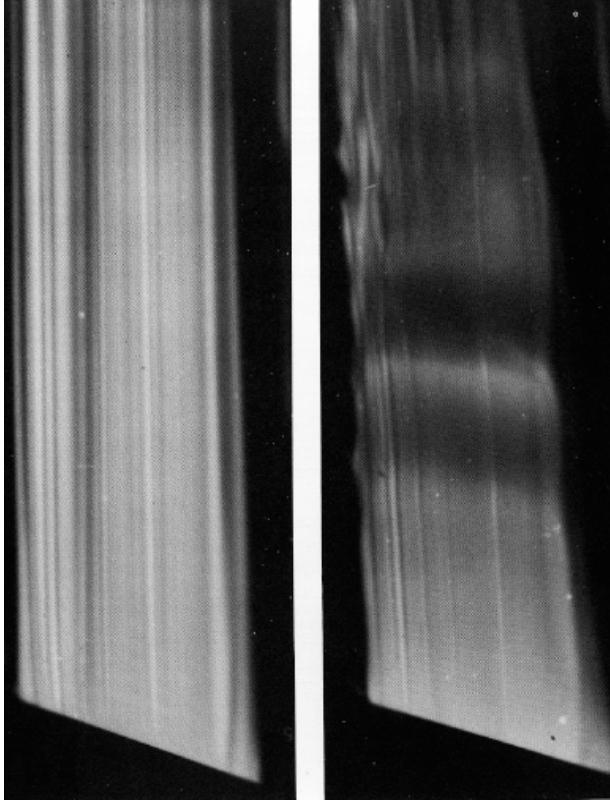


- Original 1883 apparatus
- Dye into center of pipe
- Critical $Re=13.000$
- Lower today due to traffic



History of shear flow stability and transition

- Reynolds pipe flow experiment (1883)
- Rayleigh's inflection point criterion (1887)
- Orr (1907) Sommerfeld (1908) viscous eq.
- Heisenberg (1924) viscous channel solution
- Tollmien (1931) Schlichting (1933) viscous BL solution
- Schubauer & Skramstad (1947)
experimental TS-wave verification
- Klebanoff, Tidstrom & Sargent (1962) 3D breakdown





Bypass transition

- High and low speed streaks
in the streamwise direction
- Transition due to free-
stream turbulence
- Klebanoff (1977) modes,
 $Tu > 0.5\%$ in BL
- Subcritical transition in
Poiseuille and Couette flows



Disturbance equations

$$\frac{\partial u_i}{\partial t} = -u_j \frac{\partial u_i}{\partial x_j} - \frac{\partial p}{\partial x_i} + \frac{1}{Re} \nabla^2 u_i$$

$$\frac{\partial u_i}{\partial x_i} = 0$$

$$u_i(x_i, 0) = u_i^0(x_i)$$

$$u_i(x_i, t) = 0 \quad \text{on solid boundaries}$$

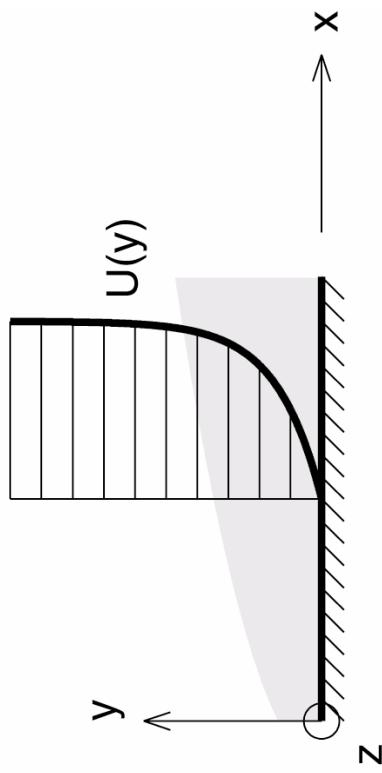
$$Re = U_\infty \delta_*/\nu$$

$$u_i = U_i + u'_i$$

$$p = P + p' \quad \text{drop primes}$$

$$\frac{\partial u_i}{\partial t} = -U_j \frac{\partial u_i}{\partial x_j} - u_j \frac{\partial U_i}{\partial x_j} - \frac{\partial p}{\partial x_i} + \frac{1}{Re} \nabla^2 u_i - u_j \frac{\partial u_i}{\partial x_j}$$

$$\frac{\partial u_i}{\partial x_i} = 0$$





Stability definitions

$$E_V = \frac{1}{2} \int_V u_i u_i \, dV.$$

Stable:

$$\lim_{t \rightarrow \infty} \frac{E_V(t)}{E_V(0)} \rightarrow 0$$

Conditionally stable:

$$\exists \quad \delta : E(0) < \delta \Rightarrow \text{stable}$$

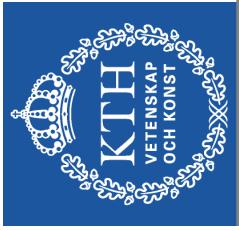
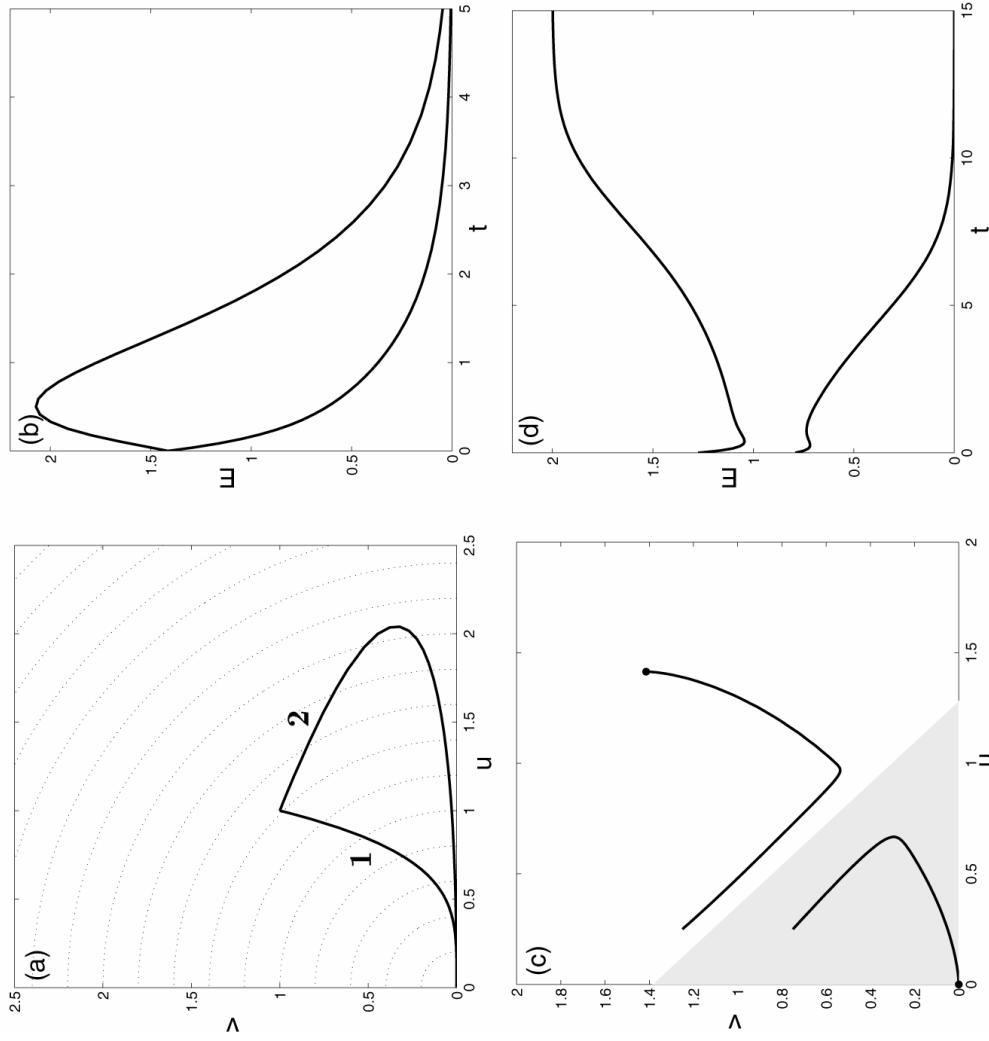
Globally stable:

Conditionally stable with $\delta \rightarrow \infty$

Monotonically stable

$$\frac{dE}{dt} \leq 0 \quad \forall \quad t > 0$$

Stability definitions

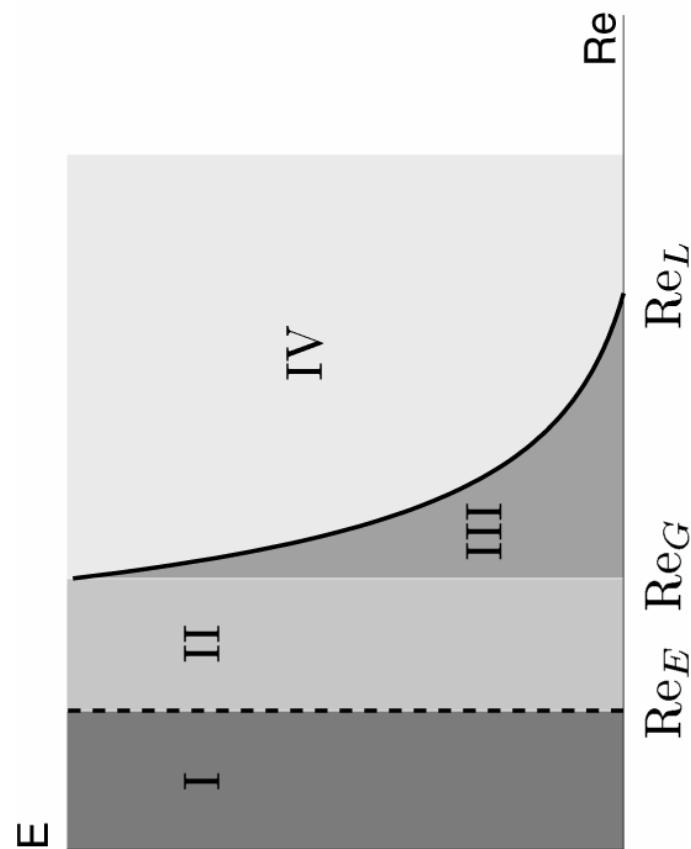


Critical Reynolds numbers

$\text{Re}_E : \text{Re} < \text{Re}_E$ flow monotonically stable

$\text{Re}_G : \text{Re} < \text{Re}_G$ flow globally stable

$\text{Re}_L : \text{Re} > \text{Re}_L$ flow linearly unstable ($\delta \rightarrow 0$)





Critical Reynolds numbers

Flow	Re_E	Re_G	Re_T	Re_L
Hagen-Poiseuille	81.5	—	2000	∞
Plane Poiseuille	49.6	—	1000	5772
Plane Couette	20.7	125	360	∞

Critical Reynolds numbers for a number of wall-bounded shear flows compiled from the literature.

Reynolds-Orr equation

$$\begin{aligned} u_i \frac{\partial u_i}{\partial t} &= -u_i u_j \frac{\partial U_i}{\partial x_j} - \frac{1}{\text{Re}} \frac{\partial u_i}{\partial x_j} \frac{\partial u_i}{\partial x_j} \\ &\quad + \frac{\partial}{\partial x_j} \left[-\frac{1}{2} u_i u_i U_j - \frac{1}{2} u_i u_i u_j - u_i p \delta_{ij} + \frac{1}{\text{Re}} u_i \frac{\partial u_i}{\partial x_j} \right] \end{aligned}$$

\Rightarrow

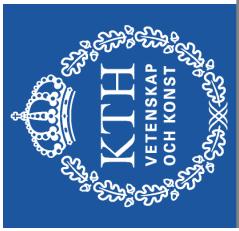
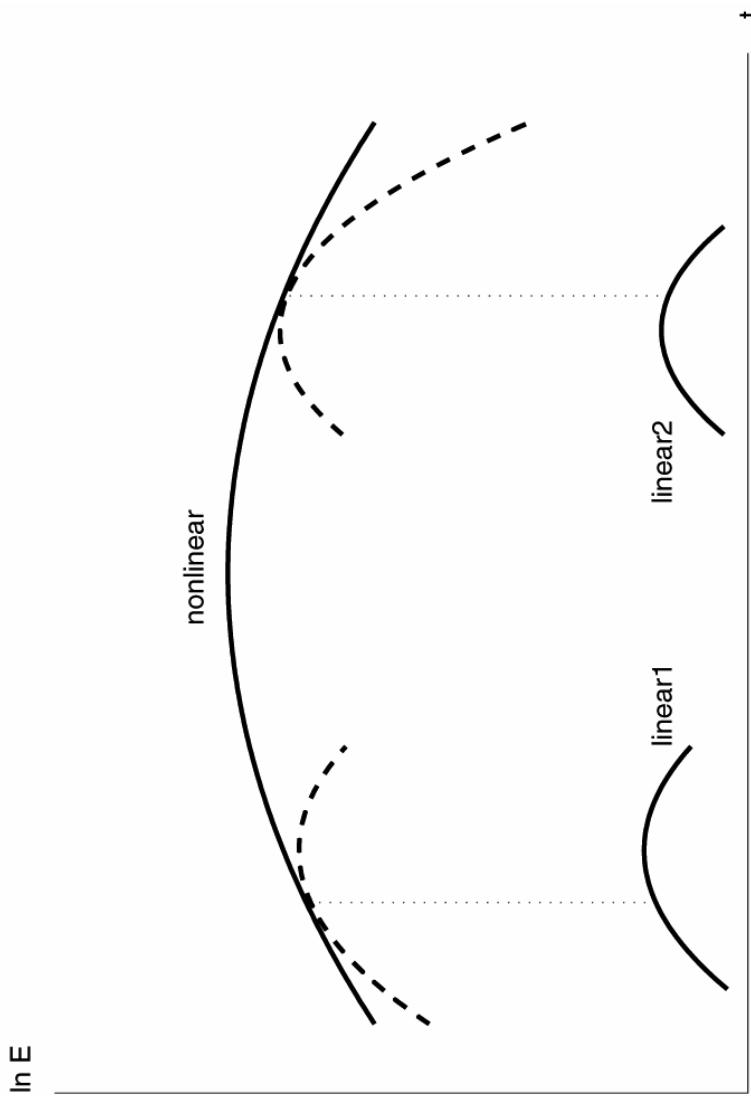
$$\frac{dE_V}{dt} = - \int_V u_i u_j \frac{\partial U_i}{\partial x_j} dV - \frac{1}{\text{Re}} \int_V \frac{\partial u_i}{\partial x_j} \frac{\partial u_i}{\partial x_j} dV$$

Theorem: Linear mechanisms required for energy growth

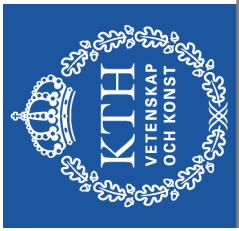
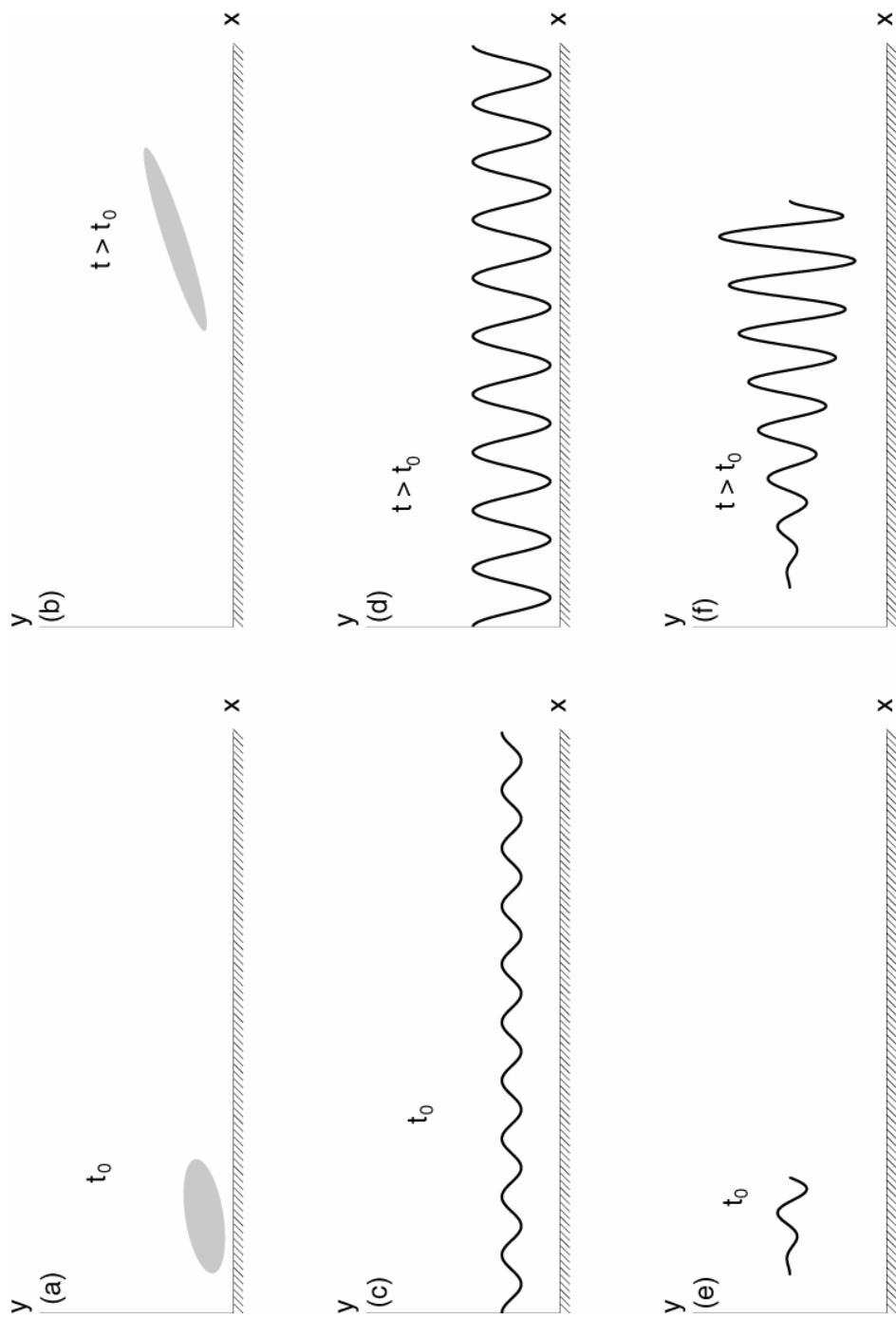
Proof: $\frac{1}{E_V} \frac{dE_V}{dt}$ independent of disturbance amplitude

Linear growth mechanisms

$$\frac{1}{E_V} \frac{dE_V}{dt} = \frac{d}{dt} \ln E_V$$



Evolution of disturbances in shear flows





Parallel shear flows: $U_i = U(y)\delta_{1i}$

$$\begin{aligned}\frac{\partial u}{\partial t} + U \frac{\partial u}{\partial x} + v U' &= -\frac{\partial p}{\partial x} + \frac{1}{Re} \nabla^2 u \\ \frac{\partial v}{\partial t} + U \frac{\partial v}{\partial x} &= -\frac{\partial p}{\partial y} + \frac{1}{Re} \nabla^2 v \\ \frac{\partial w}{\partial t} + U \frac{\partial w}{\partial x} &= -\frac{\partial p}{\partial z} + \frac{1}{Re} \nabla^2 w \\ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} &= 0.\end{aligned}$$

divergence of the momentum equations gives $\nabla^2 p = -2U' \frac{\partial v}{\partial x}$

eliminate pressure in v -equation \Rightarrow

$$\left[\left(\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \nabla^2 - U'' \frac{\partial}{\partial x} - \frac{1}{Re} \nabla^4 \right] v = 0$$



Parallel shear flows, cont

normal vorticity describes horizontal flow

$$\eta = \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x}$$

where η satisfies

$$\left[\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} - \frac{1}{Re} \nabla^2 \right] \eta = -U' \frac{\partial v}{\partial z}$$

with the boundary conditions

$v = v' = \eta = 0$ at a solid wall and in the far field



Orr-Sommerfeld and Squire equations

Assume wavelike solutions: $v(x, y, z, t) = \tilde{v}(y) e^{i(\alpha x + \beta z - \omega t)}$ \Rightarrow

$$\left[(-i\omega + i\alpha U)(D^2 - k^2) - i\alpha U'' - \frac{1}{Re} (D^2 - k^2)^2 \right] \tilde{v} = 0$$

$$\left[(-i\omega + i\alpha U) - \frac{1}{Re} (D^2 - k^2) \right] \tilde{\eta} = -i\beta U' \tilde{v}$$

Orr-Sommerfeld modes: $\{\tilde{v}_n, \tilde{\eta}_n^\rho, \omega_n\}_{n=1}^N$

Squire modes: $\{\tilde{v} = 0, \tilde{\eta}_m, \omega_m\}_{m=1}^M$



Interpretation of modal results

$$\omega = \alpha c$$

$$v = \text{Real}\{|\tilde{v}(y)| e^{i\phi(y)} e^{i[\alpha x + \beta z - \alpha(c_r + i c_i)t]}\}$$

$$= |\tilde{v}(y)| e^{\alpha c_i t} \cos[\alpha(x - c_r t) + \beta z + \phi(y)]$$

ω angular frequency

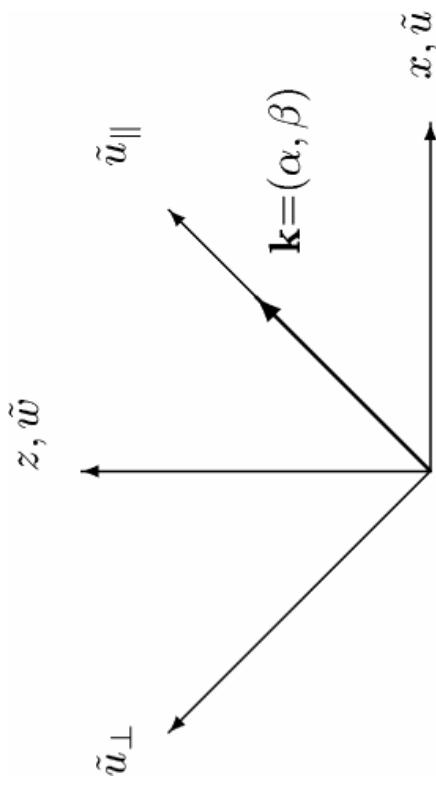
c_r phase speed

c_i temporal growthrate

α streamwise wavenumber

β spanwise wavenumber

Interpretation of modal results, cont.



$$\begin{aligned}\tilde{u}_{\parallel} &= \frac{1}{k} \begin{pmatrix} \alpha & \beta \end{pmatrix} \cdot \begin{pmatrix} \tilde{u} \\ \tilde{w} \end{pmatrix} = \frac{1}{k} (\alpha \tilde{u} + \beta \tilde{w}) = -\frac{1}{ik} \frac{d\tilde{v}}{dy} \\ \tilde{u}_{\perp} &= \frac{1}{k} \begin{pmatrix} -\beta & \alpha \end{pmatrix} \cdot \begin{pmatrix} \tilde{u} \\ \tilde{w} \end{pmatrix} = \frac{1}{k} (\alpha \tilde{w} - \beta \tilde{u}) = -\frac{1}{ik} \tilde{\eta}\end{aligned}$$



Squire's transformation

3D and 2D Orr-Sommerfeld equation with $\omega = \alpha c$

$$(U - c)(D^2 - k^2)\tilde{v} - U''\tilde{v} - \frac{1}{i\alpha \text{Re}}(D^2 - k^2)^2\tilde{v} = 0$$

$$(U - c)(D^2 - \alpha_{2D}^2)\tilde{v} - U''\tilde{v} - \frac{1}{i\alpha_{2D}\text{Re}_{2D}}(D^2 - \alpha_{2D}^2)^2\tilde{v} = 0$$

$$\alpha_{2D} = k = \sqrt{\alpha^2 + \beta^2}$$

$$\alpha_{2D}\text{Re}_{2D} = \alpha \text{Re}$$

$$\text{Re}_{2D} = \text{Re} \frac{\alpha}{k} < \text{Re}$$



Squire's theorem

Each 3D Orr-Sommerfeld mode corresponds a 2D Orr-Sommerfeld mode at a *lower* Re , *i.e.*

$$\text{Re}_{2D} = \text{Re} \frac{\alpha}{k} < \text{Re}$$
$$\Rightarrow$$

$$\text{Re}_c \equiv \min_{\alpha, \beta} \text{Re}_L(\alpha, \beta) = \min_{\alpha} \text{Re}_L(\alpha, 0)$$

since growth rate increases with Reynolds number.



Inviscid disturbances

$\text{Re} \rightarrow \infty \Rightarrow$ Rayleigh equation

$$[(-i\omega + i\alpha U)(D^2 - k^2) - i\alpha U''] \tilde{v} = 0$$

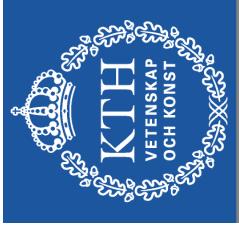
$$\omega = \alpha c \Rightarrow$$

$$\left(D^2 - k^2 - \frac{U''}{U - c} \right) \tilde{v} = 0$$

Rayleigh's inflection point criterion

Theorem: A necessary condition for *invicid* instability is
an *inflection* point in $U(y)$

$$\begin{aligned} & - \int_{-1}^1 \tilde{v}^* \left(D^2 \tilde{v} - k^2 \tilde{v} - \frac{U''}{U - c} \tilde{v} \right) dy = \\ & \int_{-1}^1 |D\tilde{v}|^2 + k^2 |\tilde{v}|^2 dy + \int_{-1}^1 \frac{U''}{U - c} |\tilde{v}|^2 dy = 0 \\ \text{Im} \left\{ \int_1^1 \frac{U''}{U - c} |\tilde{v}|^2 dy \right\} &= \int_{-1}^1 \frac{U'' c_i |\tilde{v}|^2}{|U - c|^2} dy = 0 \end{aligned}$$



Inviscid algebraic instability

$$\begin{aligned} \left(\frac{\partial}{\partial t} + i\alpha U \right) \hat{\eta} &= -i\beta U' \hat{v} && \text{where} \\ \hat{\eta}(t=0) &= \hat{\eta}_0 \end{aligned}$$

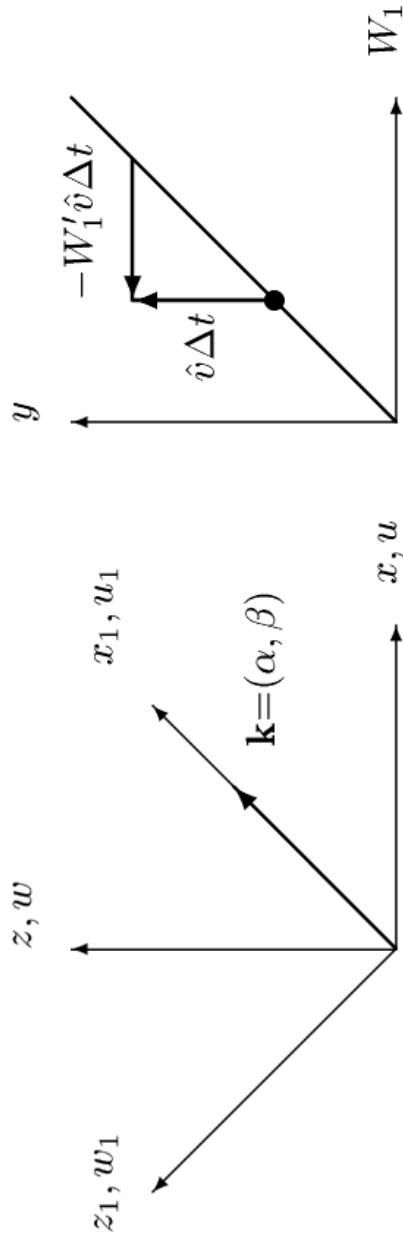
\Rightarrow

$$\hat{\eta} = \hat{\eta}_0 e^{-i\alpha Ut} - i\beta U' e^{-i\alpha Ut} \int_0^t \hat{v}(y, t') e^{i\alpha Ut'} dt'$$

for $\alpha = 0 \Rightarrow \hat{v} = \text{const} \Rightarrow$

$$\hat{\eta} = \hat{\eta}_0 - i\beta U' \hat{v}_0 t$$

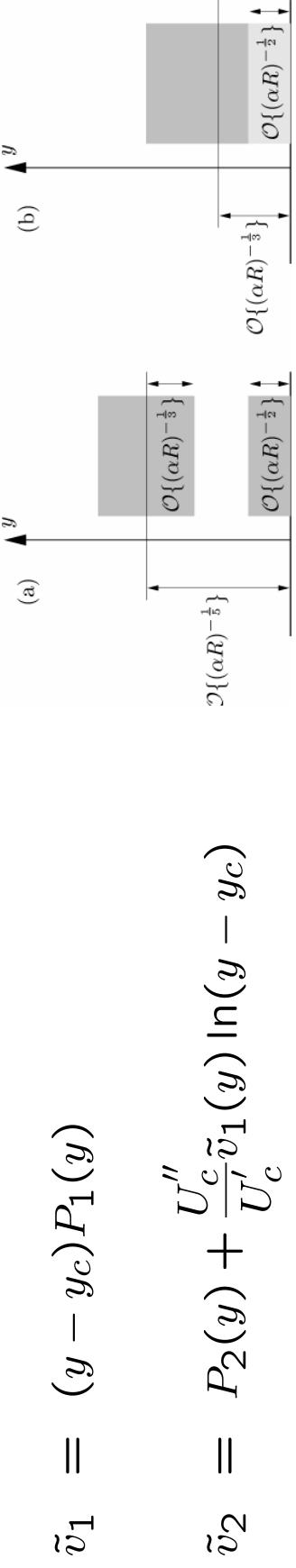
Lift-up effect



$$\begin{aligned}
 W_1 &= -\frac{\beta}{k} U \\
 \hat{w}_1 &= \frac{i}{k} \hat{\eta} \\
 \frac{D}{Dt} &= \frac{\partial}{\partial t} + i\alpha U
 \end{aligned}
 \quad
 \begin{aligned}
 \left(\frac{\partial}{\partial t} + i\alpha U \right) \hat{\eta} &= -i\beta U' \hat{v} \\
 \frac{D\hat{w}_1}{Dt} &= -W'_1 \hat{v} \\
 \Delta \hat{w}_1 &\approx -W'_1 \hat{v} \Delta t
 \end{aligned}$$

Critical Layer

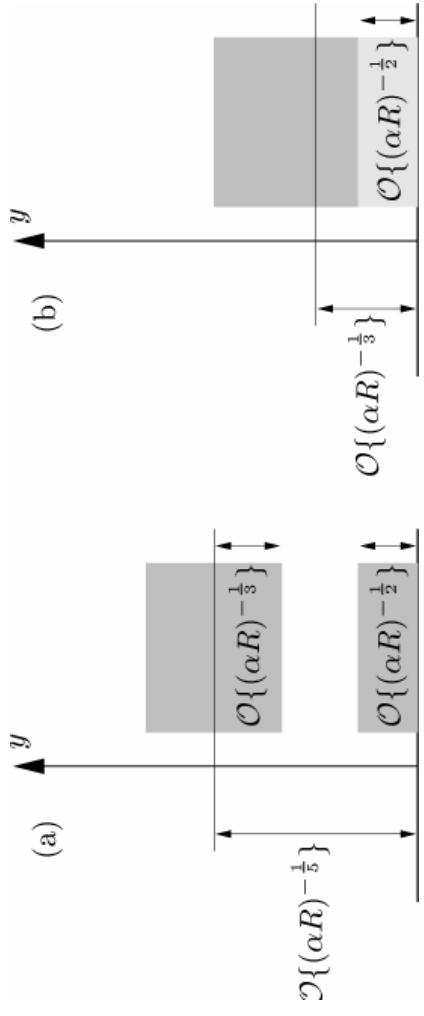
Regular singular point in Rayleigh equation at $y_c : U(y_c) = c$
 Frobenius expansion around $y = y_c \Rightarrow$



Viscous effects important in two regions

1. boundaries where BC not satisfied
2. critical layer where inviscid is singular

Thickness of critical layer



$U - c \approx U'_c(y - y_c)$ gives leading terms in OS eq.

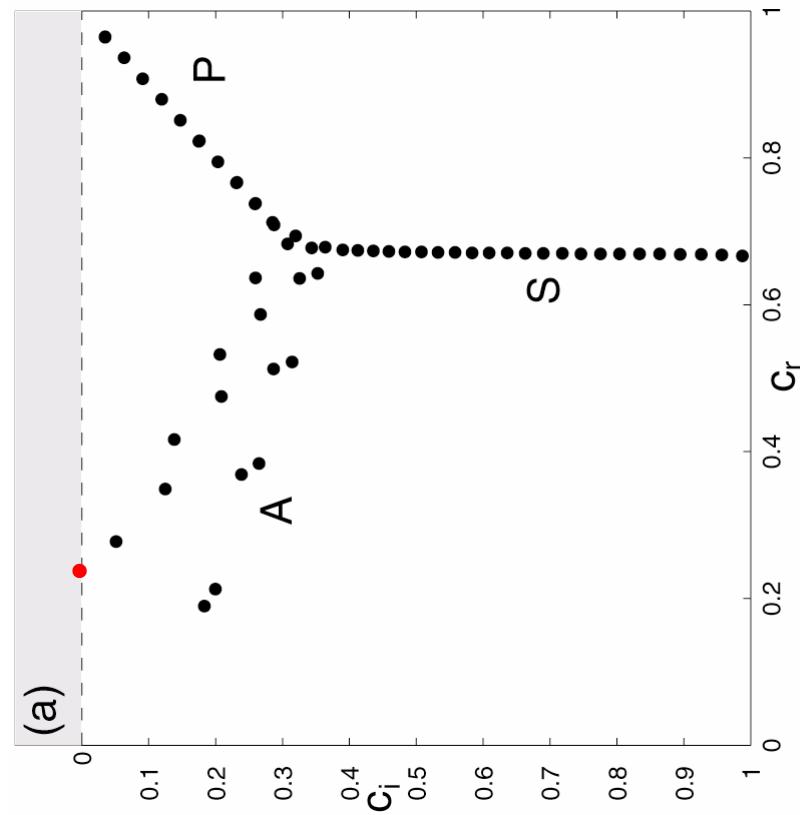
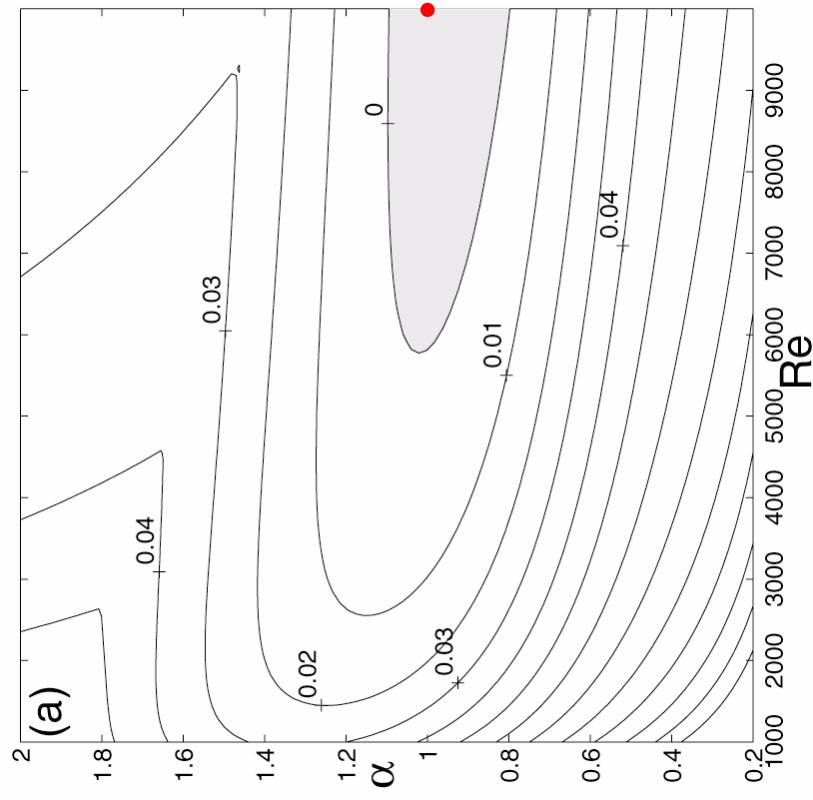
$$\frac{1}{i\alpha \text{Re}} D^4 \tilde{v} = U'_c(y - y_c) D^2 \tilde{v}$$

let $\tilde{v}(y) = V(\xi)$, $\xi = (y - y_c)/\epsilon$, $\epsilon = (i\alpha \text{Re} U'_c)^{-1/3} \Rightarrow$

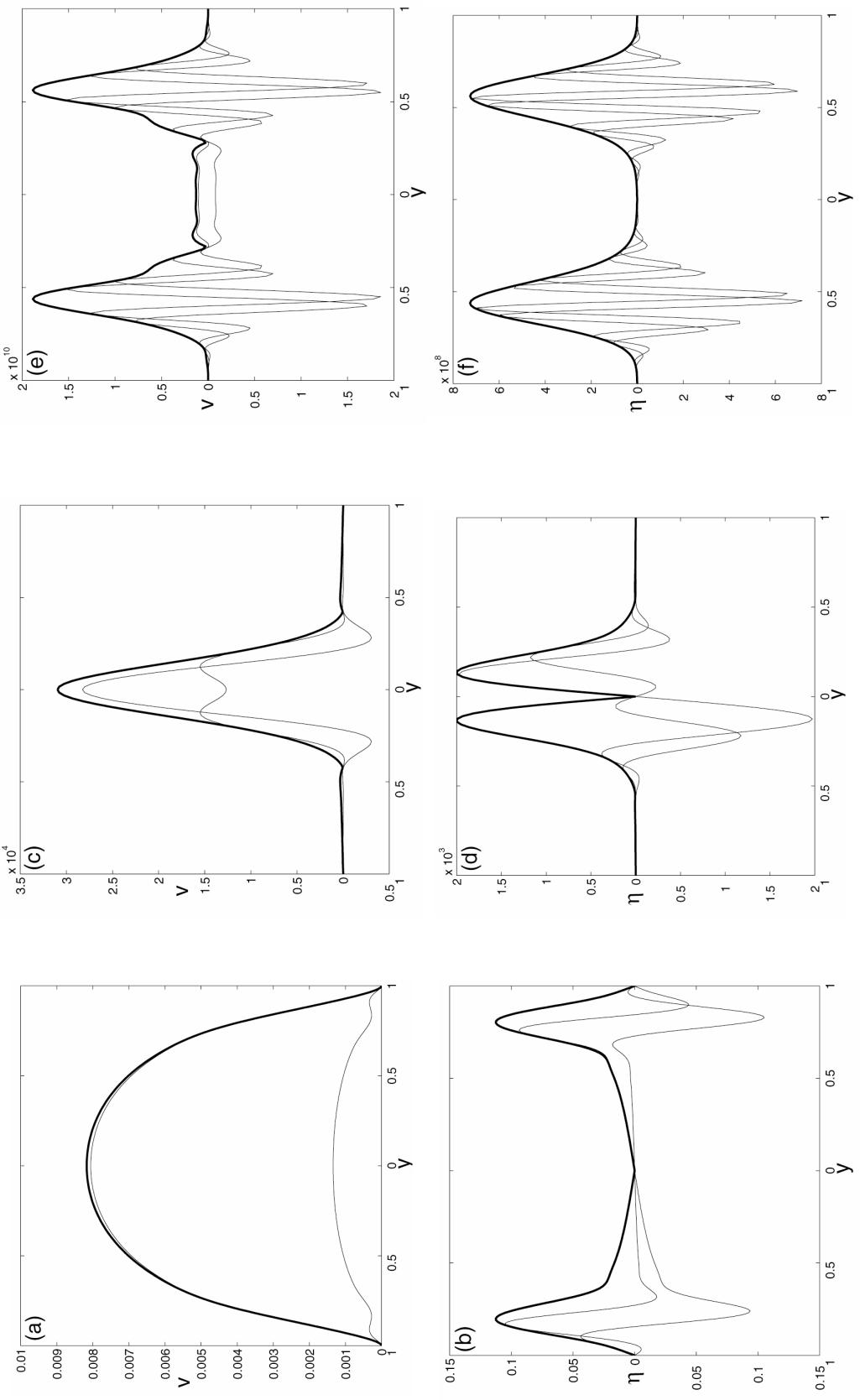
$$\left(\frac{d^2}{d\xi^2} - \xi \right) \frac{d^2}{d\xi^2} V = 0$$

Plane Poiseuille flow

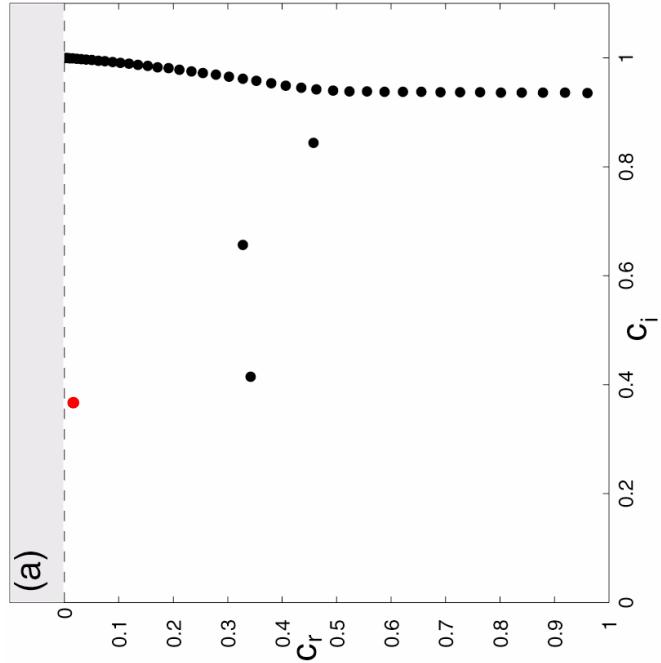
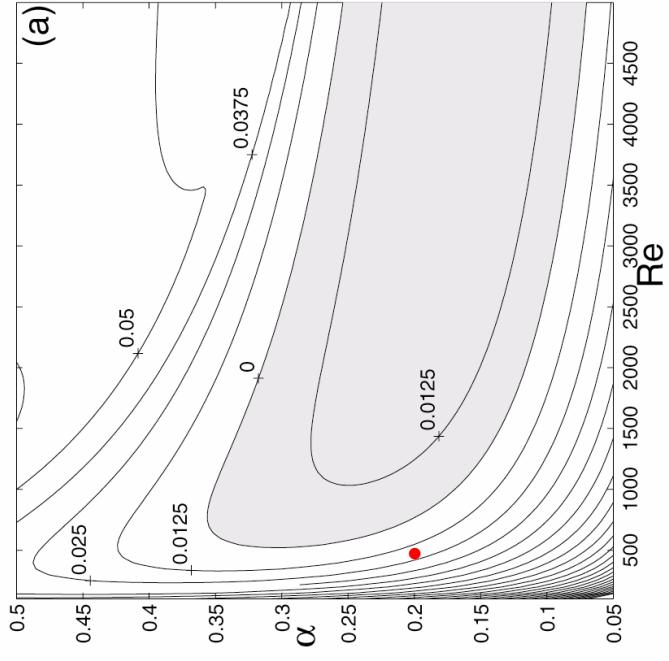
Neutral curve and spectrum



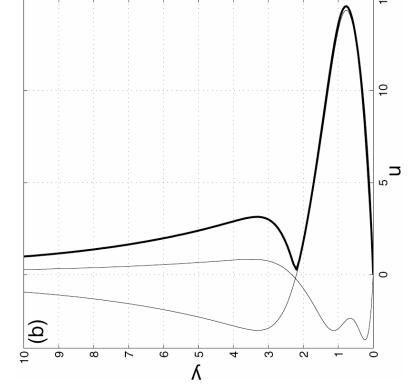
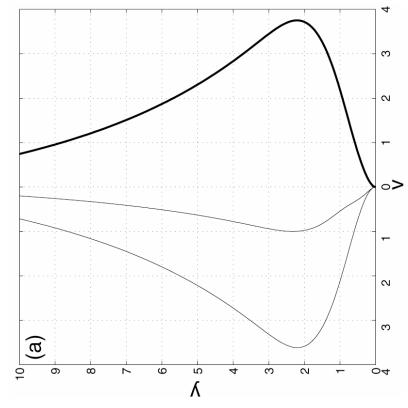
A, P, S- Eigenfunctions for PPF



Blasius boundary layer



- $Re = 500$
- $\alpha = 0.2$
- TS-mode





Continuous spectrum

$$(D^2 - k^2)^2 \hat{v} = i\alpha \operatorname{Re}[(U_\infty - c)(D^2 - k^2)] \hat{v}$$

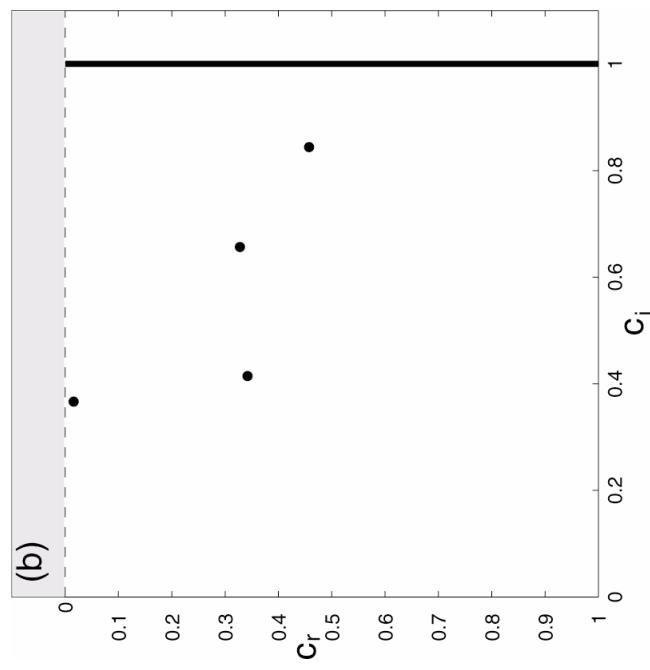
$$\hat{v}_n = \exp(\lambda_n y)$$

$$\lambda_{1,2} = \pm \sqrt{i\alpha \operatorname{Re}(U_\infty - c) + k^2}, \quad \lambda_{3,4} = \pm k$$

$\hat{v}, D\hat{v}$ bounded as $y \rightarrow \infty \Rightarrow$

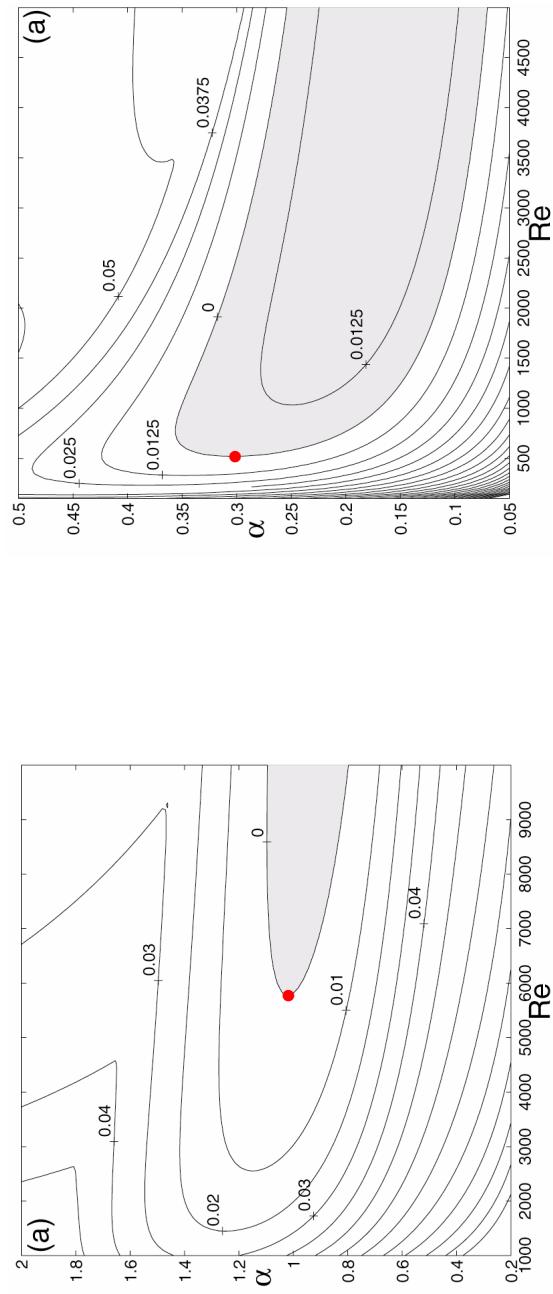
$$\alpha \operatorname{Re} c_i + k^2 < 0 \quad \alpha \operatorname{Re}(U_\infty - c_r) = 0 \quad \Rightarrow$$

$$c = U_\infty - i(1 + \xi^2) \frac{k^2}{\alpha \operatorname{Re}}$$



Critical Reynolds numbers

Flow	α_{crit}	Re_{crit}	$c_r _{crit}$
Plane Poiseuille flow	1.02	5772	0.264
Blasius boundary layer flow	0.303	519.4	0.397





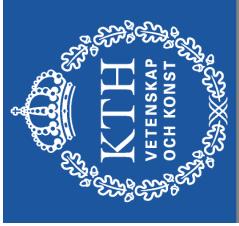
The intial value problem (IVP)

$$v(x, y, z, t) = \hat{v}(y, t) e^{i(\alpha x + \beta z)}$$

$$\eta(x, y, z, t) = \hat{\eta}(y, t) e^{i(\alpha x + \beta z)}$$

$$\begin{aligned} \left[\left(\frac{\partial}{\partial t} + i\alpha U \right) (D^2 - k^2) - i\alpha U'' - \frac{1}{Re} (D^2 - k^2)^2 \right] \hat{v} &= 0 \\ \left[\left(\frac{\partial}{\partial t} + i\alpha U \right) - \frac{1}{Re} (D^2 - k^2) \right] \hat{\eta} &= -i\beta U' \hat{v} \end{aligned}$$

$$\begin{aligned} \hat{v} &= D\hat{v} = \hat{\eta} = 0 \\ \hat{v}(t=0) &= \hat{v}_0 \\ \hat{\eta}(t=0) &= \hat{\eta}_0 \end{aligned}$$



A simple eigenfunction expansion

$$\tilde{v} = \tilde{v} e^{-i\alpha ct} \quad \text{single OS-mode}$$

$$\hat{\eta} = \sum_j C_j \tilde{\eta}_j e^{-i\alpha\sigma_j t} + \sum_k D_k \tilde{\eta}_k e^{-i\alpha ct} \Rightarrow$$

$$\sum_k D_k [U - c - \frac{1}{i\alpha \text{Re}}(D^2 - k^2)] \tilde{\eta}_k = -\frac{\beta}{\alpha} U' \tilde{v}$$

$$\sum_k D_k [\sigma_k - c] \underbrace{\int_{-1}^1 \tilde{\eta}_k \tilde{\eta}_j dy}_{\delta_{kj}} = -\frac{\beta}{\alpha} \int_{-1}^1 U' \tilde{v} \tilde{\eta}_j dy$$

$$\hat{\eta}(t=0) = 0 \Rightarrow \hat{\eta} = \sum_j \beta \int_{-1}^1 U' \tilde{v} \tilde{\eta}_j dy \frac{e^{-i\alpha ct} - e^{-i\alpha\sigma_j t}}{\alpha c - \alpha\sigma_j} \tilde{\eta}_j$$



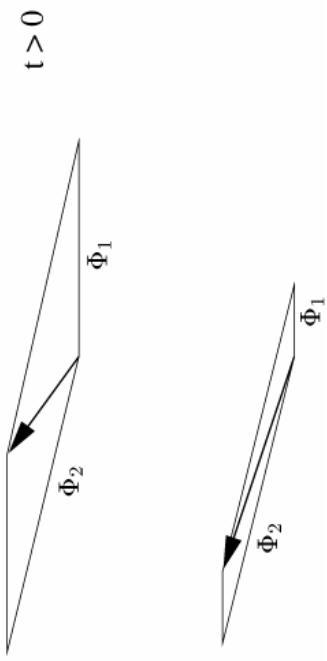
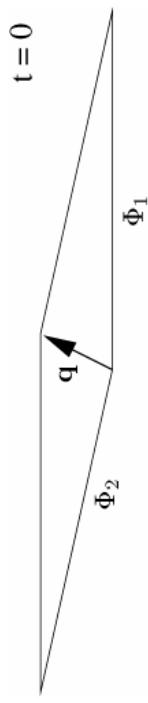
Transient growth

$$\alpha \rightarrow 0 \Rightarrow \omega^{OS} = \alpha c = -i\mu/\text{Re}$$

$$\omega_j^{SQ} = \alpha \sigma_j = -i\nu_j/\text{Re}$$

$$\begin{aligned}\hat{\eta} &= \sum_j \frac{i\beta \text{Re} \int_{-1}^1 U' \tilde{v} \tilde{\eta}_j dy}{\mu - \nu_j} (e^{-\mu t/\text{Re}} - e^{-\nu_j t/\text{Re}}) \tilde{\eta}_j \\ &= \underbrace{\sum_j \tilde{\eta}_j \int_{-1}^1 U' \tilde{v} \tilde{\eta}_j dy}_{U' \tilde{v}} [-i\beta t + O(t^2/\text{Re})] \\ &= -i\beta U' \tilde{v}_0 t + O(t^2/\text{Re})\end{aligned}$$

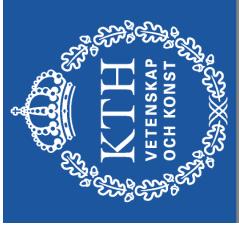
Model with non-orthogonal eigenfunctions



$$\frac{d}{dt} \begin{pmatrix} v \\ \eta \end{pmatrix} = \begin{pmatrix} -\frac{1}{Re} & 0 \\ 1 & -\frac{2}{Re} \end{pmatrix} \begin{pmatrix} v \\ \eta \end{pmatrix}$$

$$\begin{pmatrix} v \\ \eta \end{pmatrix} = v_0 \begin{pmatrix} 1 \\ Re \end{pmatrix} e^{-t/Re} + (\eta_0 - v_0 Re) \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^{-2t/Re}$$

$$\eta(t) = \eta_0 e^{-2t/Re} + \underbrace{\text{Re } v_0 (e^{-t/Re} - e^{-2t/Re})}_{v_0 t - \frac{3v_0}{Re} t^2 + \dots}$$



General formulation of viscous IVP

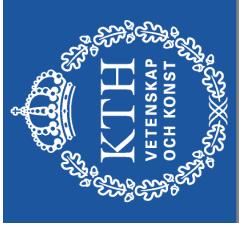
$$\frac{\partial}{\partial t} \underbrace{\begin{pmatrix} -D^2 + k^2 & 0 \\ 0 & 1 \end{pmatrix}}_{\mathbf{M}} \begin{pmatrix} \hat{v} \\ \hat{\eta} \end{pmatrix} = \underbrace{\begin{pmatrix} \mathcal{L}_{OS} & 0 \\ -i\beta U' & \mathcal{L}_{SQ} \end{pmatrix}}_{\mathbf{L}} \underbrace{\begin{pmatrix} \hat{v} \\ \hat{\eta} \end{pmatrix}}_{\hat{\mathbf{q}}}$$

$$\mathcal{L}_{OS} = -i\alpha U(k^2 - D^2) - i\alpha U'' - \frac{1}{Re}(k^2 - D^2)^2$$

$$\mathcal{L}_{SQ} = -i\alpha U - \frac{1}{Re}(k^2 - D^2).$$

$$\frac{\partial}{\partial t} \mathbf{M} \hat{\mathbf{q}} = \mathbf{L} \hat{\mathbf{q}}$$

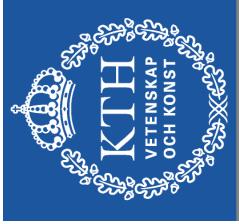
$$\frac{\partial}{\partial t} \hat{\mathbf{q}} = \mathbf{M}^{-1} \mathbf{L} \hat{\mathbf{q}} = \mathbf{L}_1 \hat{\mathbf{q}}$$



Disturbance measure

$$E_V = \int_{\alpha} \int_{\beta} E \, d\alpha \, d\beta$$

$$\begin{aligned} E &= \frac{1}{2} \int_{-1}^1 \left(|\hat{u}|^2 + |\hat{v}|^2 + |\hat{u}|^2 \right) \, dy \\ &= \frac{1}{2k^2} \int_{-1}^1 \left(|D\hat{v}|^2 + k^2 |\hat{v}|^2 + |\hat{\eta}|^2 \right) \, dy \\ &= \frac{1}{2k^2} \int_{-1}^1 \begin{pmatrix} \hat{v} \\ \hat{\eta} \end{pmatrix}^H \begin{pmatrix} -D^2 - k^2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \hat{v} \\ \hat{\eta} \end{pmatrix} \, dy \\ 2k^2 E &= \int_{-1}^1 \hat{\mathbf{q}}^H \mathbf{M} \hat{\mathbf{q}} \, dy = (\hat{\mathbf{q}}, \hat{\mathbf{q}}) = \|\hat{\mathbf{q}}\|^2 \end{aligned}$$



Adjoint OS-SQ system

$$\begin{aligned} (\tilde{\mathbf{q}}^+, \mathbf{L}_1 \tilde{\mathbf{q}}) &= \int_{-1}^1 \tilde{\mathbf{q}}^{+H} \mathbf{M} \mathbf{L}_1 \tilde{\mathbf{q}} dy \\ &= \int_{-1}^1 \begin{pmatrix} \tilde{\xi} \\ \tilde{\zeta} \end{pmatrix}^H \begin{pmatrix} \mathcal{L}_{OS}^+ & 0 \\ i\beta U' & \mathcal{L}_{SQ}^+ \end{pmatrix} \begin{pmatrix} \tilde{v} \\ \tilde{\eta} \end{pmatrix} dy \\ &= \int_{-1}^1 [\tilde{\xi}^* \mathcal{L}_{OS} \tilde{v} + i\beta U' \tilde{\zeta}^* \tilde{v} + \tilde{\zeta}^* \mathcal{L}_{SQ} \tilde{\eta}] dy = \{\text{integration by parts}\} \\ &= \int_{-1}^1 [(\mathcal{L}_{OS}^+ \tilde{\xi})^* \tilde{v} - (i\beta U' \tilde{\zeta})^* \tilde{v} + (\mathcal{L}_{SQ}^+ \tilde{\zeta})^* \tilde{\eta}] dy \\ &= \int_{-1}^1 \left[\begin{pmatrix} \mathcal{L}_{OS}^+ & -i\beta U' \\ 0 & \mathcal{L}_{SQ}^+ \end{pmatrix} \begin{pmatrix} \tilde{\xi} \\ \tilde{\zeta} \end{pmatrix} \right]^H \begin{pmatrix} \tilde{v} \\ \tilde{\eta} \end{pmatrix} dy \\ &= \int_{-1}^1 [\mathbf{M} \mathbf{L}_1^+ \tilde{\mathbf{q}}^+]^H \tilde{\mathbf{q}} dy \\ &= (\mathbf{L}_1^+ \tilde{\mathbf{q}}^+, \tilde{\mathbf{q}}) \end{aligned}$$



Biorthogonality

$$\frac{\partial}{\partial t} \hat{\mathbf{q}} = \mathbf{L}_1 \hat{\mathbf{q}}, \quad \hat{\mathbf{q}} = \tilde{\mathbf{q}} e^{\lambda t} \quad \Rightarrow$$

$$0 = (\tilde{\mathbf{q}}^+, (\mathbf{L}_1 - \lambda \mathbf{I}) \tilde{\mathbf{q}}) = ((\mathbf{L}_1^+ - \lambda^* \mathbf{I}) \tilde{\mathbf{q}}^+, \tilde{\mathbf{q}})$$

$$0 = (\tilde{\mathbf{q}}_n^+, \mathbf{L}_1 \tilde{\mathbf{q}}_m) - (\mathbf{L}_1^+ \tilde{\mathbf{q}}_n^+, \tilde{\mathbf{q}}_m)$$

$$= (\tilde{\mathbf{q}}_n^+, \lambda_m \tilde{\mathbf{q}}_m) - (\lambda_n^* \tilde{\mathbf{q}}_n^+, \tilde{\mathbf{q}}_m)$$

$$= (\lambda_m - \lambda_n) \underbrace{(\tilde{\mathbf{q}}_n^+, \tilde{\mathbf{q}}_m)}_{\delta_{mn}}$$



Component form of adjoint

$$\lambda^* \underbrace{\begin{pmatrix} -D^2 + k^2 & 0 \\ 0 & 1 \end{pmatrix}}_{\mathbf{M}} \begin{pmatrix} \tilde{\xi} \\ \zeta \end{pmatrix} = \underbrace{\begin{pmatrix} \mathcal{L}_{OS}^+ & i\beta U' \\ 0 & \mathcal{L}_{SQ}^+ \end{pmatrix}}_{\mathbf{L}^+} \underbrace{\begin{pmatrix} \tilde{\xi} \\ \zeta \end{pmatrix}}_{\hat{\mathbf{q}}^+}$$

$$\mathcal{L}_{OS}^+ = i\alpha U(k^2 - D^2) - i\alpha 2U'D - \frac{1}{Re}(k^2 - D^2)^2$$

$$\mathcal{L}_{SQ}^+ = i\alpha U - \frac{1}{Re}(k^2 - D^2).$$

Adjoint Orr-Sommerfeld modes:

$$\left\{ \tilde{\xi}_n, \tilde{\zeta} = 0, \omega_n \right\}_{n=1}^N$$

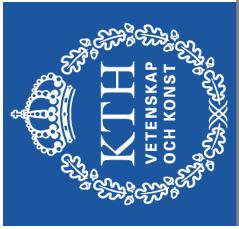
Adjoint Squire modes:

$$\left\{ \tilde{\xi}_m^p, \tilde{\zeta}_m, \omega_m \right\}_{m=1}^M$$

Solution of IVP using eigenfunction expansions

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} \hat{\mathbf{q}} = \mathbf{M}^{-1} \mathbf{L} \hat{\mathbf{q}} = \mathbf{L}_1 \hat{\mathbf{q}} \quad \hat{\mathbf{q}}(t=0) = \hat{\mathbf{q}}_0 \\ \\ \|\hat{\mathbf{q}}\|^2 = (\hat{\mathbf{q}}, \hat{\mathbf{q}}) = \int_{-1}^1 \hat{\mathbf{q}}^H \mathbf{M} \hat{\mathbf{q}} \ dy \end{array} \right.$$

$$\begin{aligned} \hat{\mathbf{q}} &= \sum_{n=1}^{\infty} \kappa_n^0 \tilde{\mathbf{q}}_n e^{\lambda_n t} \Rightarrow \\ (\tilde{\mathbf{q}}_m^+, \hat{\mathbf{q}}_0) &= \left(\tilde{\mathbf{q}}_m^+, \sum_{n=1}^{\infty} \kappa_n^0 \tilde{\mathbf{q}}_n \right) = \sum_{n=1}^{\infty} \kappa_n^0 (\tilde{\mathbf{q}}_m^+, \tilde{\mathbf{q}}_n) = \kappa_m^0 \end{aligned}$$



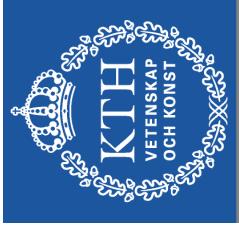


Discrete formulation

Project solution on $S^N = \text{span}\{\tilde{\mathbf{q}}_1, \tilde{\mathbf{q}}_2, \dots, \tilde{\mathbf{q}}_N\}$

$$\hat{\mathbf{q}} = \sum_{n=1}^N \kappa_n^0 \tilde{\mathbf{q}}_n e^{\lambda_n t} = \sum_{n=1}^N \kappa_n(t) \tilde{\mathbf{q}}_n \quad \hat{\mathbf{q}} \in S^N$$

$$\kappa = \begin{pmatrix} \kappa_1 \\ \vdots \\ \kappa_N \end{pmatrix} = \begin{pmatrix} e^{\lambda_1 t} & & \\ & \ddots & \\ & & e^{\lambda_N t} \end{pmatrix} \begin{pmatrix} \kappa_1^0 \\ \vdots \\ \kappa_N^0 \end{pmatrix} = e^{\Lambda t} \kappa^0$$



Discrete formulation, cont.

$$\|\hat{\mathbf{q}}\|^2 = (\hat{\mathbf{q}}, \hat{\mathbf{q}}) = \sum_{m=1}^N \sum_{n=1}^N \kappa_m \kappa_n^* (\tilde{\mathbf{q}}_n, \tilde{\mathbf{q}}_m) \quad \hat{\mathbf{q}} \in S^N$$

$$\begin{aligned} &= \begin{pmatrix} \kappa_1^* & \dots & \kappa_N^* \end{pmatrix} \begin{pmatrix} (\tilde{\mathbf{q}}_1, \tilde{\mathbf{q}}_1) & (\tilde{\mathbf{q}}_1, \tilde{\mathbf{q}}_2) \\ \vdots & \ddots \\ & (\tilde{\mathbf{q}}_N, \tilde{\mathbf{q}}_N) \end{pmatrix} \begin{pmatrix} \kappa_1 \\ \vdots \\ \kappa_N \end{pmatrix} \\ &= \kappa^H A \kappa \\ &= \kappa^H F^H F \kappa \quad F^H F = A \quad \text{Hermitian} \\ &= \|F\kappa\|_2^2 \quad 2\text{-norm, sum of squares} \\ &= \|\kappa\|_E^2 \quad \text{energy norm} \end{aligned}$$

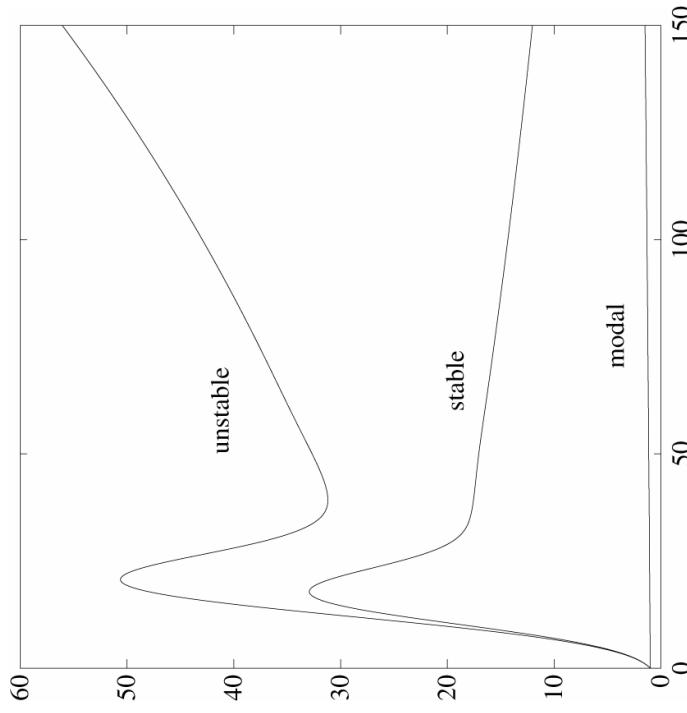


Maximum amplification

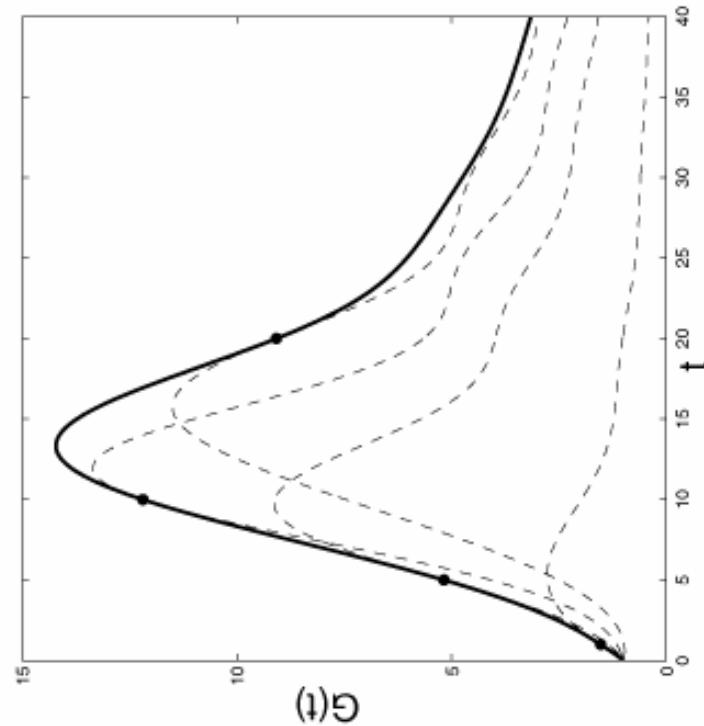
$$\begin{aligned} G(t) &= \max_{\hat{\mathbf{q}}_0 \neq 0} \frac{\|\hat{\mathbf{q}}(t)\|^2}{\|\hat{\mathbf{q}}_0\|^2} \\ &= \max_{\kappa_0 \neq 0} \frac{\|\kappa\|_E^2}{\|\kappa_0\|_E^2} \\ &= \max_{\kappa_0 \neq 0} \frac{\|e^{\Lambda t} \kappa_0\|_E^2}{\|\kappa_0\|_E^2} \\ &= \max_{\kappa_0 \neq 0} \frac{\|F e^{\Lambda t} F^{-1} F \kappa_0\|_2^2}{\|F \kappa_0\|_2^2} \\ &= \underbrace{\|F e^{\Lambda t} F^{-1}\|_B}_{} \|F \kappa_0\|_2^2 \\ &\leq \|F\|_2^2 \|F^{-1}\|_2^2 \|e^{\Lambda t}\|_2^2 = \text{cond}(F)^2 e^{2\Re\{\lambda_{max}\}t} \end{aligned}$$

$$\|B\|_2^2 = \lambda_{max}(B^H B) = \sigma_1^2(B) \quad \text{for } F \kappa_0 = v_1$$

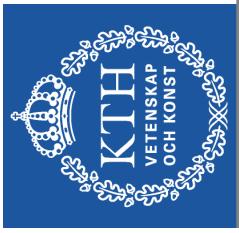
2D PPF: envelope and selected IC



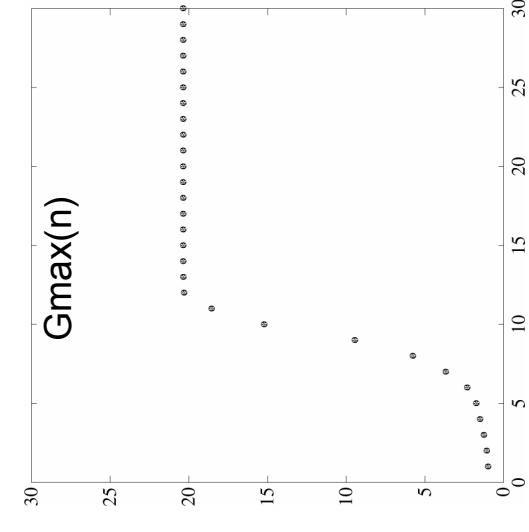
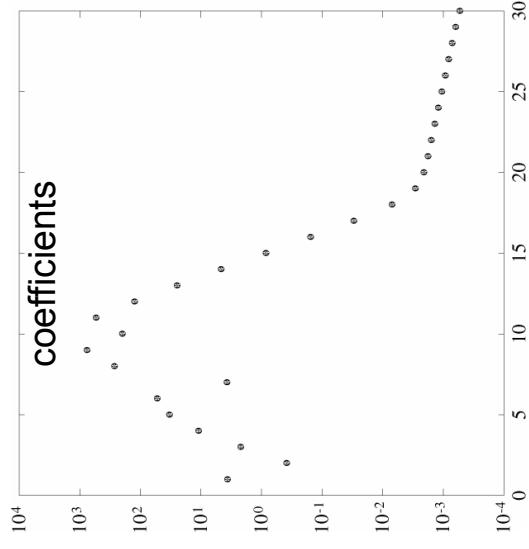
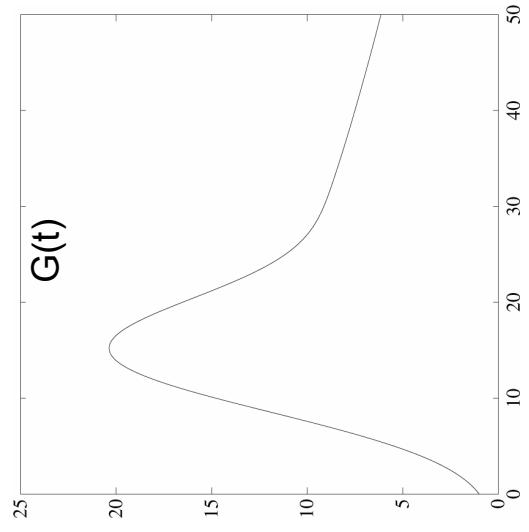
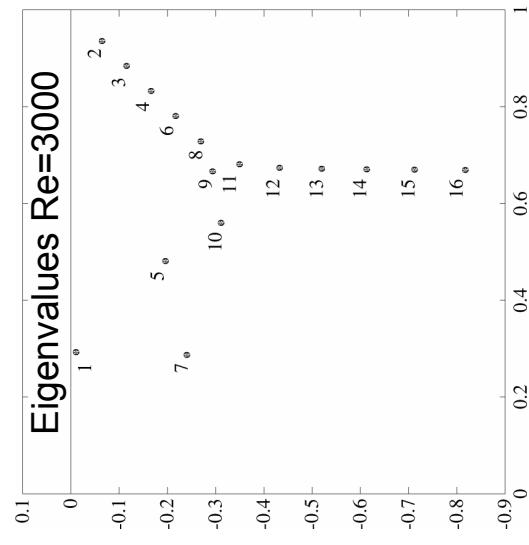
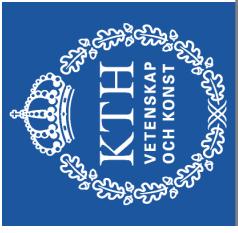
Re=5000, 8000



Re=1000

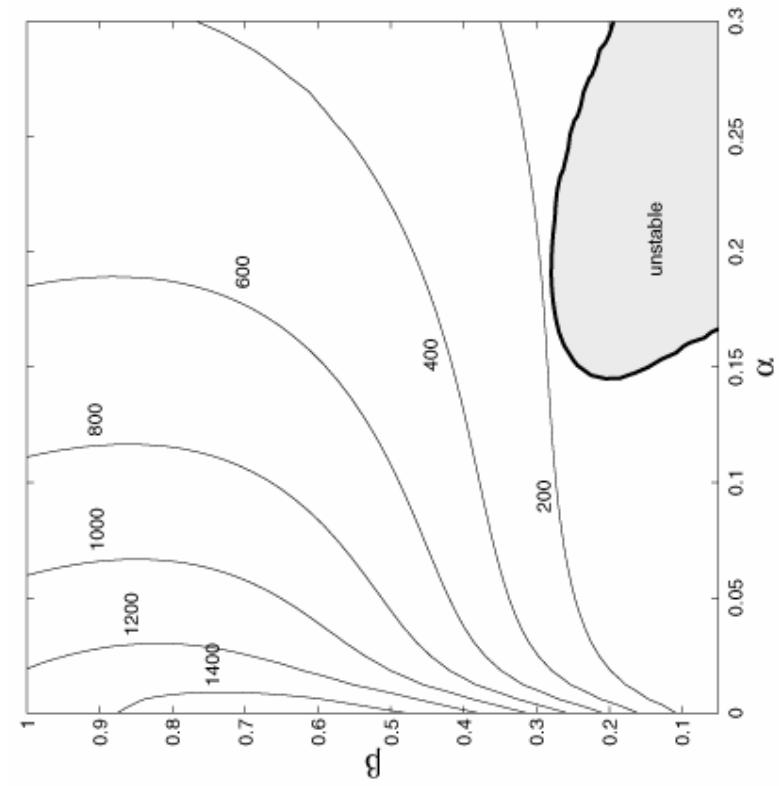
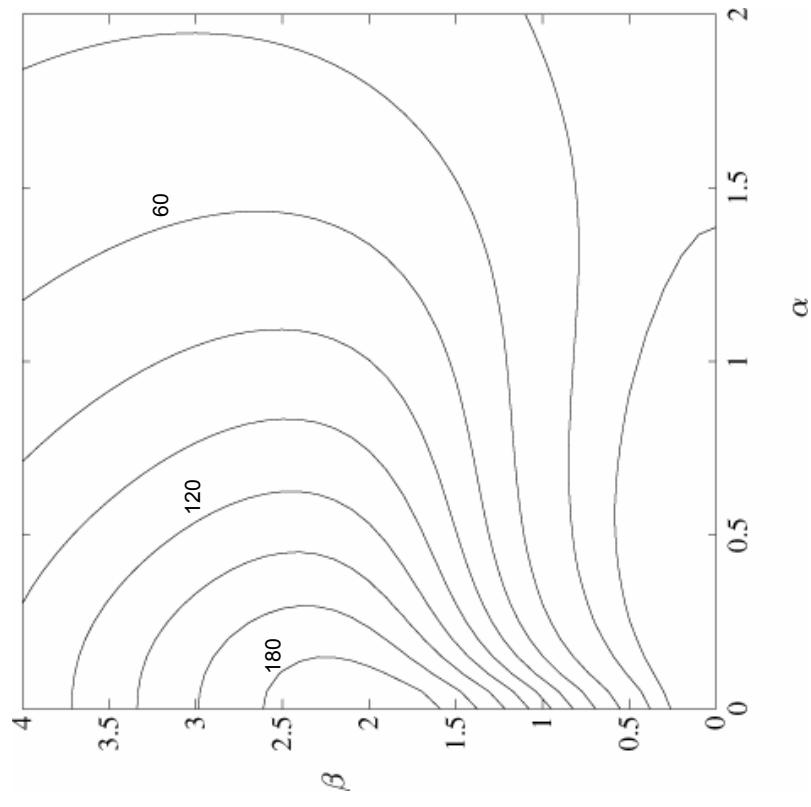


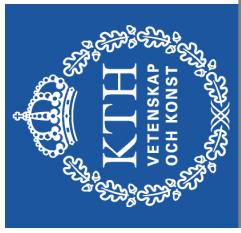
2D PPF: dependence on N



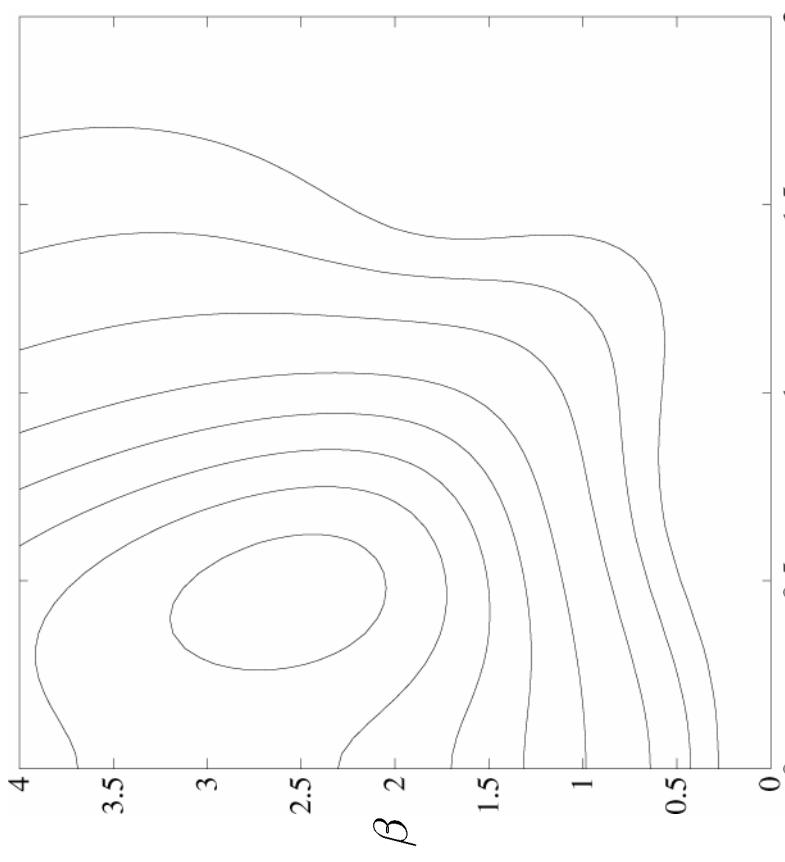
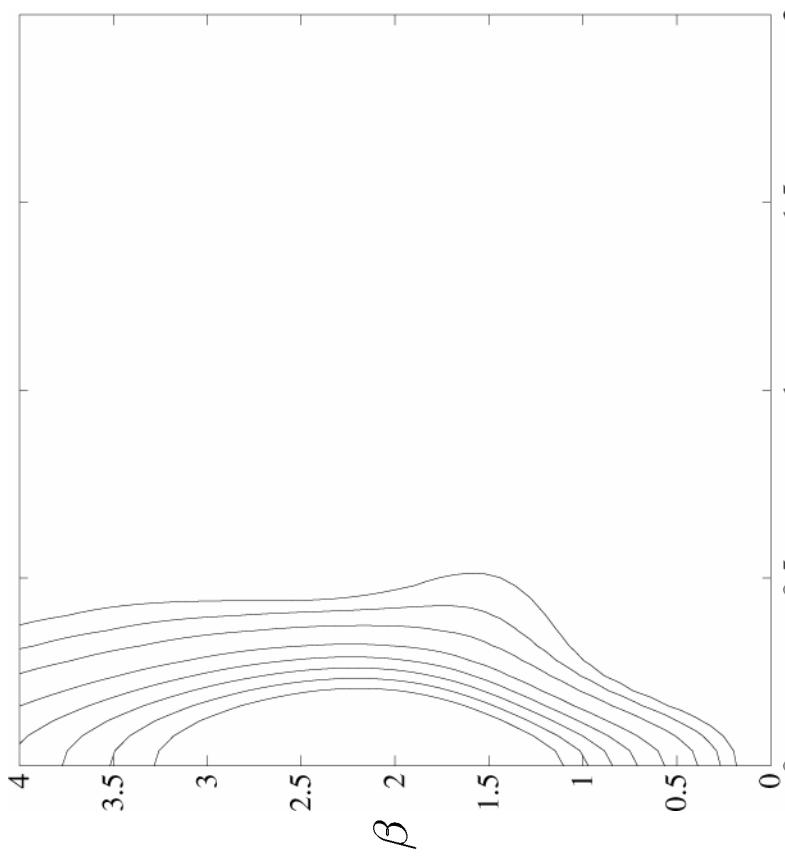
3D PPF and Blasius flow, $\text{Re}=1000$

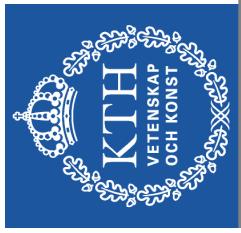
$$G_{max} = \max_{t \geq 0} G(t)$$





3D PPF: $G(t)$, $Re=1000$

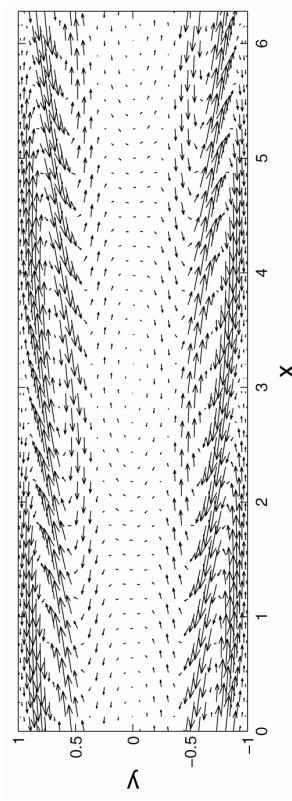




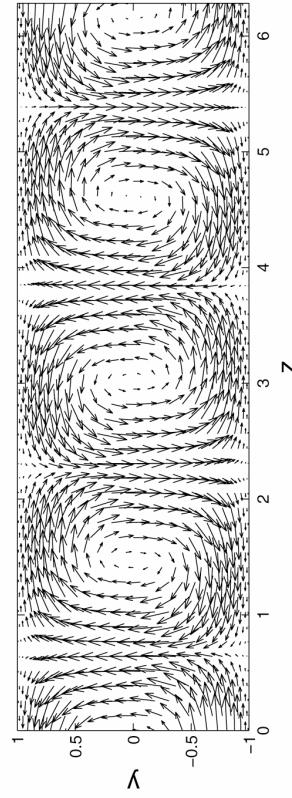
Optimal disturbances PPF, Re=1000

$t = 0$

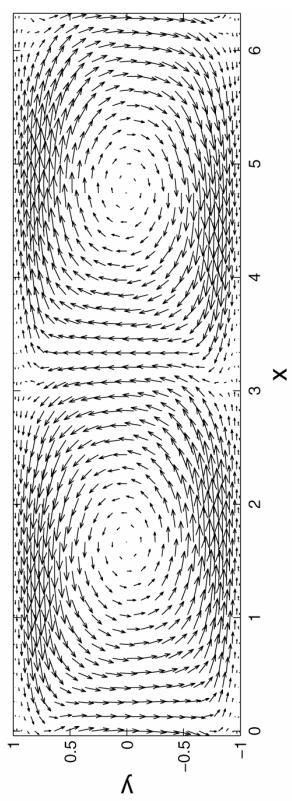
2D disturbance



3D disturbance



$t = t_{max}$



$\alpha = 1, \beta = 0$ $\alpha = 0, \beta = 2$



The forced problem and the resolvent

$$\frac{\partial}{\partial t} \hat{\mathbf{q}} = \mathbf{L}_1 \hat{\mathbf{q}} + \hat{\mathbf{q}}_f e^{i\omega t} \Rightarrow$$

$$\hat{\mathbf{q}} = e^{\mathbf{L}_1 t} \hat{\mathbf{q}}_0 + (\mathbf{L}_1 - i\omega \mathbf{I})^{-1} \hat{\mathbf{q}}_f e^{i\omega t}$$

$$\frac{\partial}{\partial t} \hat{\mathbf{q}} = \mathbf{L}_1 \hat{\mathbf{q}} \quad \tilde{\mathbf{q}} = \int_0^\infty e^{-st} \hat{\mathbf{q}}(t) dt$$

$$s\tilde{\mathbf{q}} - \mathbf{L}_1 \tilde{\mathbf{q}} = \hat{\mathbf{q}}_0$$

$$\tilde{\mathbf{q}} = (s\mathbf{I} - \mathbf{L}_1)^{-1} \hat{\mathbf{q}}_0$$



Discrete formulation

$$\begin{aligned}\tilde{\mathbf{q}} &= \int_0^\infty e^{-st} \tilde{\mathbf{q}}(t) dt \\ &= \int_0^\infty e^{-st} \sum_{n=1}^N \kappa_n \tilde{\mathbf{q}}_n e^{\lambda_n t} dt \\ &= \sum_{n=1}^N \kappa_n \tilde{\mathbf{q}}_n \int_0^\infty e^{-(s-\lambda_n)t} dt \\ &= \sum_{n=1}^N \frac{\kappa_n}{s - \lambda_n} \tilde{\mathbf{q}}_n \\ \kappa(s) &= \begin{pmatrix} \frac{1}{s - \lambda_1} & \cdots & \frac{\kappa_1^0}{s - \lambda_N} \\ & \ddots & \\ & & \frac{1}{s - \lambda_N} \end{pmatrix} \begin{pmatrix} \kappa_1^0 \\ \vdots \\ \kappa_N^0 \end{pmatrix}\end{aligned}$$



Maximum response to forcing

$$\begin{aligned} R(s) &= \max_{\hat{\mathbf{q}}_0 \neq 0} \frac{\|(s\mathbf{I} - \mathbf{L}_1)^{-1}\hat{\mathbf{q}}_0\|}{\|\hat{\mathbf{q}}_0\|} \\ &= \max_{\kappa_0 \neq 0} \frac{\|\kappa(s)\|_E}{\|\kappa_0\|_E} \\ &= \|F \text{ diag}\left\{\frac{1}{s - \lambda_1}, \dots, \frac{1}{s - \lambda_N}\right\} F^{-1}\|_2 \\ &\leq \|F\|_2 \|F^{-1}\| \frac{1}{\min.\text{dist}(\lambda - s)} \end{aligned}$$

Pseudospectra, resolvents and sensitivity

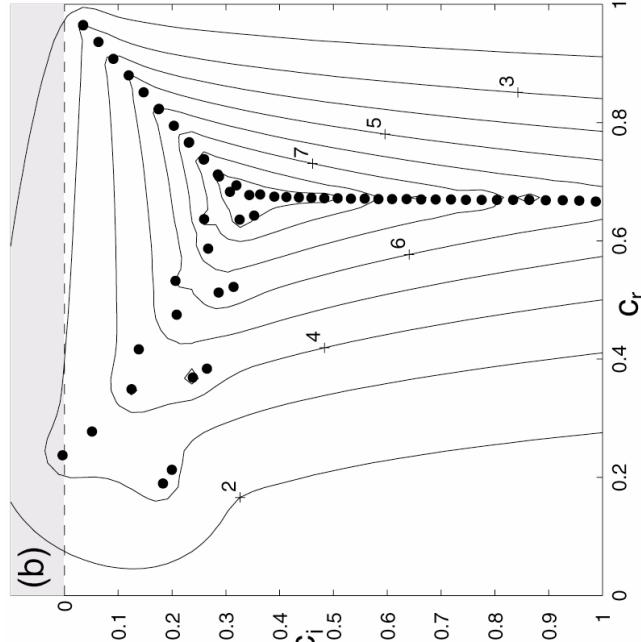
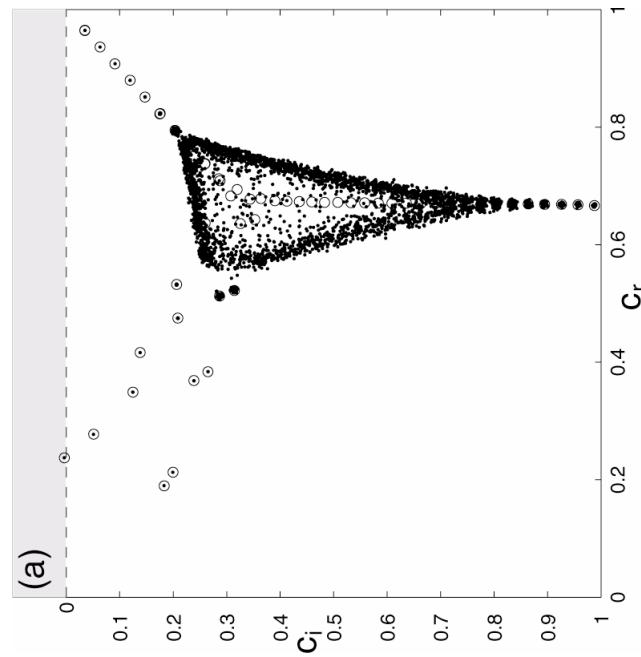
Definition: for $\epsilon \geq 0$, s is in the ϵ -pseudospectra of L if any of the following equivalent conditions hold

(i)

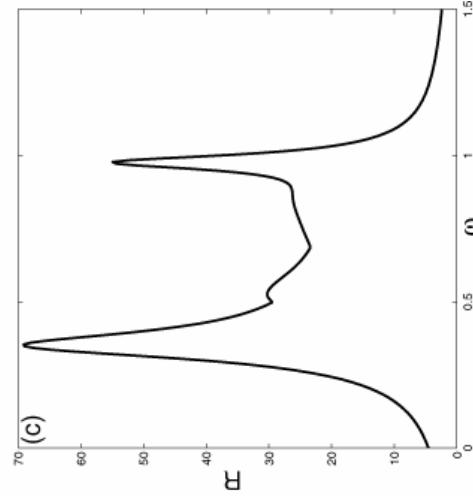
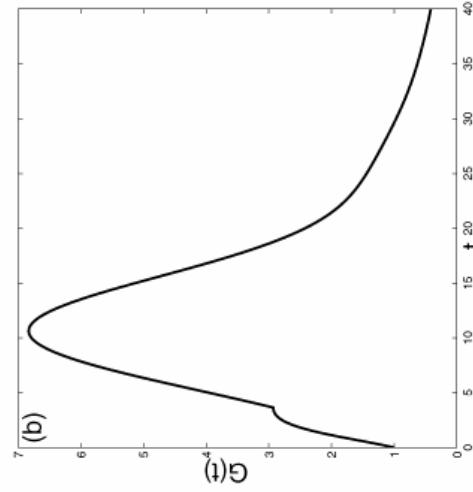
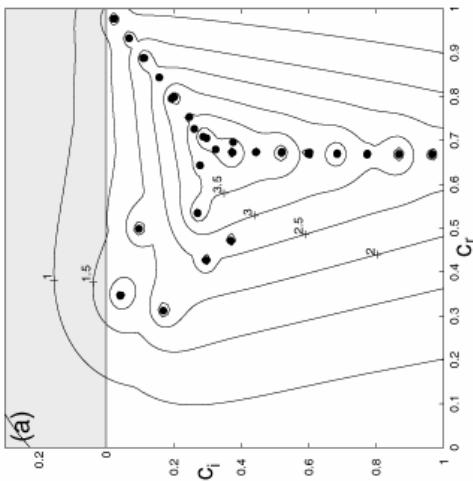
s is an eigenvalue of $L + E$, where $\|E\| \leq \epsilon$

(ii)

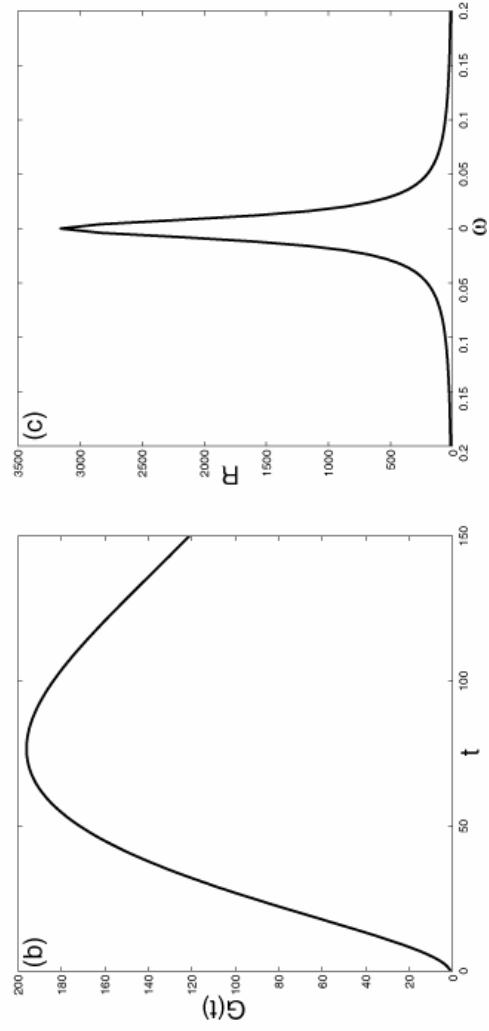
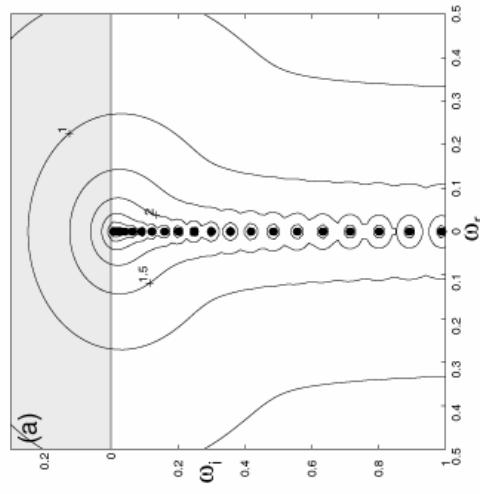
$$\|(sI - L)^{-1}\| \geq \frac{1}{\epsilon}$$



PPF: resolvents, growth and forcing



PPF: resolvents, growth and forcing



Re-dependence of growth and response

scaling:

$$\bar{t} = t/\text{Re}, \quad \bar{\eta}(y, \bar{t}) = \hat{\eta}(y, t/\text{Re})/\beta\text{Re}, \quad \bar{v}(y, \bar{t}) = \hat{v}(y, t/\text{Re}) \quad \Rightarrow$$

$$\frac{\partial}{\partial t} \underbrace{\begin{pmatrix} -D^2 + k^2 & 0 \\ 0 & 1 \end{pmatrix}}_{\mathbf{M}} \begin{pmatrix} \bar{v} \\ \bar{\eta} \end{pmatrix} = \underbrace{\begin{pmatrix} \bar{\mathcal{L}}_{OS} & 0 \\ -iU' & \bar{\mathcal{L}}_{SQ} \end{pmatrix}}_{\bar{\mathbf{L}}} \underbrace{\begin{pmatrix} \bar{v} \\ \bar{\eta} \end{pmatrix}}_{\bar{\mathbf{q}}}$$

$$\bar{\mathcal{L}}_{OS} = -i\alpha\text{Re}U(k^2 - D^2) - i\alpha\text{Re}U'' - (k^2 - D^2)^2$$

$$\bar{\mathcal{L}}_{SQ} = -i\alpha\text{Re}U - k^2 + D^2$$



Re-dependence, cont.

for $\alpha \text{Re} = 0$ all eigensolutions are damped and

$$\begin{aligned}\mathcal{L}_{OS} \text{ normal} &\Rightarrow E_V(\bar{t}) \leq E_V(0) \\ \mathcal{L}_{SQ} \text{ normal} &\Rightarrow E_\eta(\bar{t}) \leq E_\eta(0) \text{ if } \bar{v}_0 = 0\end{aligned}$$

$$\begin{aligned}2k^2 E(\bar{t}) &= \|\bar{\mathbf{q}}\|^2 = \int_{-1}^1 (k^2 |\bar{v}|^2 + |D\bar{v}|^2 + \beta^2 \text{Re}^2 |\bar{\eta}|^2) dy \\ &= E_V(\bar{t}) + \beta^2 \text{Re}^2 E_\eta(\bar{t})\end{aligned}$$

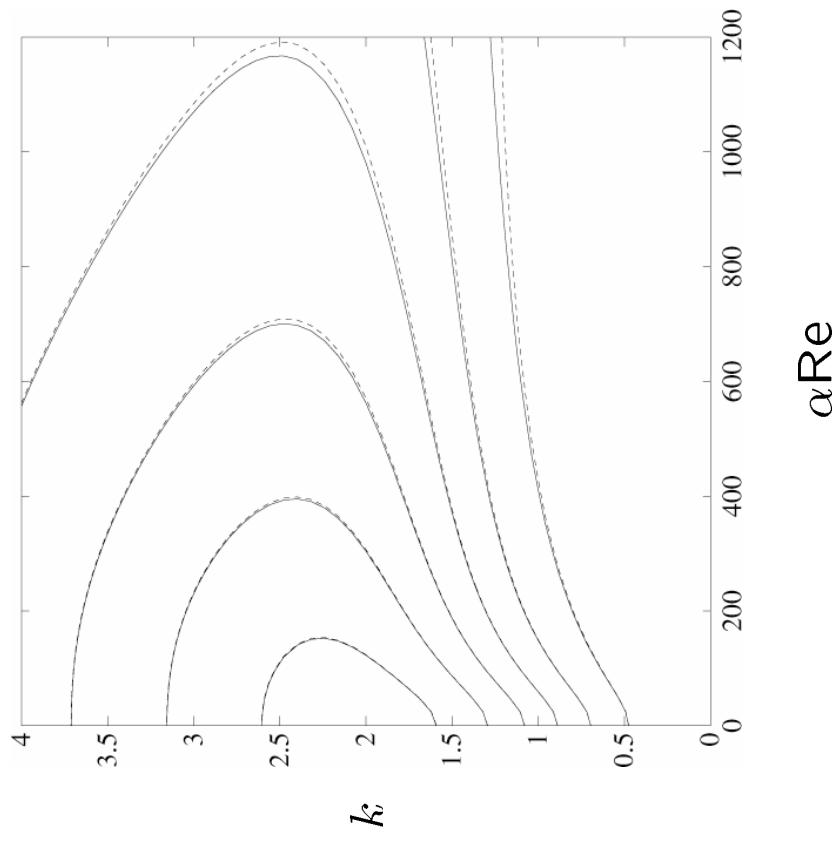
$$G(\bar{t}_{max}) = \max \frac{E_V(\bar{t}_{max}) + \beta^2 \text{Re}^2 E_\eta(\bar{t}_{max})}{E_V(0) + \beta^2 \text{Re}^2 E_\eta(0)}$$

$$\approx \beta^2 \text{Re}^2 \max \frac{E_\eta(\bar{t}_{max})}{E_V(0)}$$



Re-dependence of Gmax for PPF

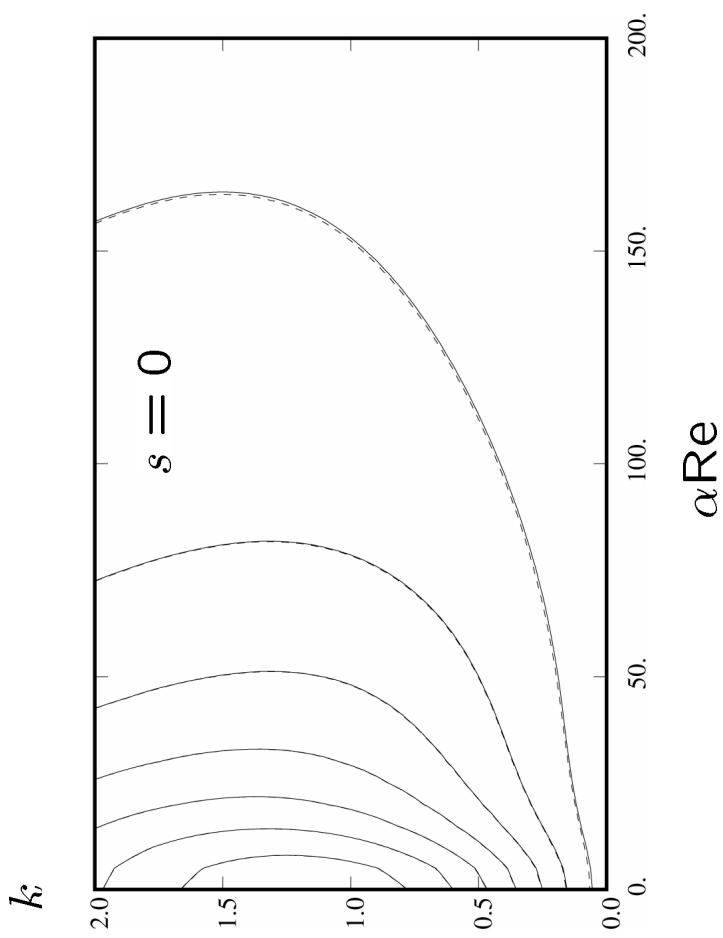
$\frac{k^2 G(\bar{t}_{max})}{\beta^2 Re^2}$ depends only on k and αRe





Re-dependence of R_{max} for PCF

$$\begin{aligned}(s\mathbf{I} - \mathbf{L})^{-1} &= \int_0^{\infty} e^{-st} \hat{\mathbf{q}}(t) dt \\&= \int_0^{\infty} e^{-\bar{s}\bar{t}} \bar{\mathbf{q}}(\bar{t}) \text{Re} d\bar{t} \\&= \text{Re}(\bar{s}\mathbf{I} - \bar{\mathbf{L}})^{-1}\end{aligned}$$



$\frac{k^2 \| (s\mathbf{I} - \mathbf{L})^{-1} \|^2}{\beta^2 \text{Re}^4}$ depends only on k and αRe

Re-dependence of G_{max} and R_{max}

Flow	G_{max} (10^{-3})	t_{max}	α	β
plane Poiseuille	0.20 Re^2	0.076 Re	0	2.04
plane Couette	1.18 Re^2	0.117 Re	$35/\text{Re}$	1.6
circular pipe	0.07 Re^2	0.048 Re	0	1
Blasius boundary layer	1.50 Re^2	0.778 Re	0	0.65

Flow	$\max_{\omega \in \mathcal{R}} R(\omega)$	α	β
plane Poiseuille	$(\text{Re}/17.4)^2$	0	1.62
plane Couette	$(\text{Re}/8.12)^2$	0	1.18
Blasius boundary layer	$(\text{Re}/1.83)^2$	0	0.21