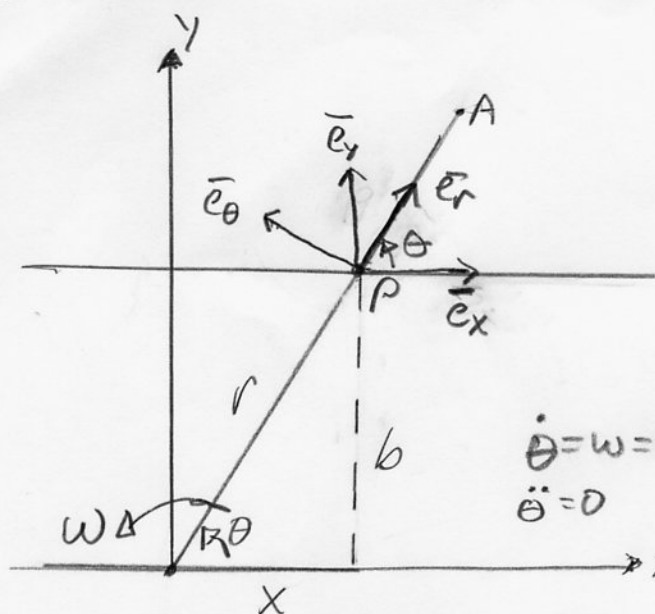


7.15



I. Direkt i Kartesiska
Komponenter

$$\vec{v} = \dot{x}\vec{e}_x + \dot{y}\vec{e}_y$$

$$\vec{a} = \ddot{x}\vec{e}_x + \ddot{y}\vec{e}_y$$

$$y = b = \text{konst} \Rightarrow \dot{y} = 0 \text{ och } \ddot{y} = 0$$

$$v_x = \dot{x} \quad a_x = \ddot{x} \quad v_y = 0 \quad a_y = 0$$

$$x = r \cos \theta \quad \text{Eliminera } r!$$

$$r = \frac{b}{\sin \theta} \Rightarrow x = b \frac{\cos \theta}{\sin \theta}$$

$$\dot{x} = b \left(-\frac{\dot{\theta} \sin \theta}{\sin^2 \theta} - \frac{\dot{\theta} \cos \theta \cos \theta}{\sin^2 \theta} \right)$$

$$\dot{x} = -b\omega \left(1 + \frac{\cos^2 \theta}{\sin^2 \theta} \right)$$

$$\dot{x} = -b\omega \frac{\sin^2 \theta + \cos^2 \theta}{\sin^2 \theta}$$

$$\dot{x} = -b\omega \frac{1}{\sin^2 \theta}$$

$$v_x = -\frac{b\omega}{\sin^2 \theta} \quad (1)$$

$$\ddot{x} = -b\omega \left(-2\omega \frac{\cos \theta}{\sin^3 \theta} \right)$$

$$a_x = 2b\omega^2 \frac{\cos \theta}{\sin^3 \theta} \quad (2)$$

$$\sin \theta > 0 \text{ för } 0 < \theta < \pi$$

(1): $v_x < 0$ alltid Partikeln P rör sig åt vänster

$$\cos \theta \geq 0 \text{ för } 0 < \theta \leq \frac{\pi}{2}$$

$$\cos \theta \leq 0 \text{ för } \frac{\pi}{2} \leq \theta < \pi$$

$$(2): a_x \geq 0 \text{ för } 0 < \theta \leq \frac{\pi}{2}$$

$$a_x \leq 0 \text{ för } \frac{\pi}{2} \leq \theta < \pi$$

$$a_x = 0 \text{ för } \theta = \frac{\pi}{2}$$

x Accelerationen

> 0 Åt höger

= 0 Åt vänster

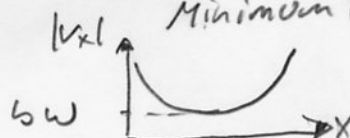
< 0 0

Farten $|v_x|$

Minskar ($> b\omega$)

Ökar ($> b\omega$)

Minimum ($= b\omega$)



7.15 (forts)

II Cylinderkomponenter

(planpolära komponenter där $z=0$)

$$\vec{V} = \underbrace{\dot{r}}_{V_r} \vec{e}_r + \underbrace{r\dot{\theta}}_{V_\theta} \vec{e}_\theta \quad (\dot{z} = \ddot{z} = 0)$$

$$\vec{a} = (\underbrace{\ddot{r}}_{a_r} - \underbrace{r\dot{\theta}^2}_{a_\theta}) \vec{e}_r + (2\dot{r}\dot{\theta} + \underbrace{r\ddot{\theta}}_{a_\theta}) \vec{e}_\theta$$

$$\dot{\theta} = \omega \quad \ddot{\theta} = 0$$

$$r = \frac{b}{\sin \theta}$$

$$\frac{d}{dt} \left(\frac{1}{\sin \theta} \right) = \frac{d}{d\theta} \left(\frac{1}{\sin \theta} \right) \frac{d\theta}{dt} = -\dot{\theta} \frac{\cos \theta}{\sin^2 \theta}$$

enl förra sidan

$$\dot{r} = -\frac{b\dot{\theta} \cos \theta}{\sin^2 \theta}$$

$$\dot{r} = -b\omega \frac{\cos \theta}{\sin^2 \theta} \quad V_r = -b\omega \frac{\cos \theta}{\sin^2 \theta} \quad V_\theta = r\dot{\theta} = b\omega \frac{1}{\sin \theta}$$

$$\ddot{r} = -b\omega \left(-\frac{\dot{\theta} \sin \theta}{\sin^2 \theta} - \frac{2\dot{\theta} \cos^2 \theta}{\sin^3 \theta} \right) = b\omega^2 \frac{\sin^2 \theta + 2\cos^2 \theta}{\sin^3 \theta}$$

se förra sidan

$$a_r = \ddot{r} - \underbrace{r\dot{\theta}^2}_{\omega^2} = b\omega^2 \frac{\sin^2 \theta + 2\cos^2 \theta}{\sin^3 \theta} - b\omega^2 \frac{1}{\sin \theta} =$$

$$= b\omega^2 \frac{\sin^2 \theta + 2\cos^2 \theta - \sin^2 \theta}{\sin^3 \theta} = 2b\omega^2 \frac{\cos^2 \theta}{\sin^3 \theta}$$

$$a_\theta = 2\dot{r}\dot{\theta} + \underbrace{r\ddot{\theta}}_0 = -2b\omega^2 \frac{\cos \theta}{\sin^2 \theta}$$

$$\vec{e}_r = \cos \theta \vec{e}_x + \sin \theta \vec{e}_y$$

$$\vec{e}_\theta = -\sin \theta \vec{e}_x + \cos \theta \vec{e}_y$$

$$\vec{V} = V_r \vec{e}_r + V_\theta \vec{e}_\theta = -b\omega \frac{\cos \theta}{\sin^2 \theta} (\cos \theta \vec{e}_x + \sin \theta \vec{e}_y) + b\omega \frac{1}{\sin \theta} (-\sin \theta \vec{e}_x + \cos \theta \vec{e}_y)$$

$$\vec{V} = -b\omega \left(\frac{\cos^2 \theta}{\sin^2 \theta} + 1 \right) \vec{e}_x + 0 \vec{e}_y$$

$$V_x = -b\omega \frac{\cos^2 \theta + \sin^2 \theta}{\sin^2 \theta}$$

$$V_x = -\frac{b\omega}{\sin^2 \theta}$$

$$V_y = 0$$

7.15 (forts)

$$\begin{aligned}\bar{a} &= a_r \bar{e}_r + a_\theta \bar{e}_\theta = 2b\omega^2 \frac{\cos^2 \theta}{\sin^3 \theta} (\cos \theta \bar{e}_x + \sin \theta \bar{e}_y) - \\ &\quad - 2b\omega^2 \frac{\cos \theta}{\sin^2 \theta} (-\sin \theta \bar{e}_x + \cos \theta \bar{e}_y)\end{aligned}$$

$$\bar{a} = 2b\omega^2 \underbrace{\left(\frac{\cos^3 \theta}{\sin^3 \theta} + \cos \theta \right)}_{a_x} \bar{e}_x + \underbrace{0}_{a_y} \bar{e}_y$$

$$a_x = 2b\omega^2 \frac{\cos \theta (\cos^2 \theta + \sin^2 \theta)}{\sin^3 \theta} = 2b\omega^2 \frac{\cos \theta}{\sin^3 \theta}$$

$$\boxed{a_x = 2b\omega^2 \frac{\cos \theta}{\sin^3 \theta}} \quad \boxed{a_y = 0}$$

GK