Simulation of spatially evolving flow past a sphere in a stratified fluid Matthew B. de Stadler, Advisor: Prof. Sutanu Sarkar

Motivation

Flow past a sphere is an established benchmark problem as it combines fully three-dimensional unsteady flow dynamics with a transition to turbulence. The presence of a density gradient significantly complicates matters as it destroys the symmetry of the problem and introduces a complex coupling between kinetic and potential energy. The standard approach for numerical simulation of flow past a sphere in a density stratified fluid is to use a temporal approximation to relate time evolution in an auxiliary domain not resolving the sphere to distance downstream of the sphere in a spatial frame. Very few simulations resolving the sphere in the computational domain have been performed and those that have are characterized by low Reynolds number or the use of turbulence models. The goal of the present study is to simulate spatially evolving flow past a sphere at high Reynolds number without the use of turbulence models. **Principal motivation:** To characterize the near to intermediate wake region as buoyancy effects become significant

Background



Wake evolution in the vertical, x_3 , and horizontal, x_2 , directions. Curvy arrows show the time when internal waves are significant and pancake eddies are shown in the late wake.

Formulation

Simulation details

Direct numerical simulation

Collocated grid arrangement using pressure-correction algorithm Semi-implicit mixed RK3-ADI method for time advancement

RK3 for convective terms, ADI for diffusive terms 2nd order centered differences for spatial derivatives Multigrid pressure solver

3D domain decomposition, parallelization with MPICH-II

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Infinitely far away

Uniform undisturbed inflow

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	\rightarrow	
	\rightarrow	(D)
	\rightarrow	$x_{3\uparrow}$
	\rightarrow	$\langle \rho \rangle \longrightarrow x_1$

Governing equations

3D incompressible, unsteady Navier-Stokes equations, Boussinesq approx.

Momentum	$rac{\partial u_i}{\partial t}$ -	$+ \frac{\partial \left(u_k u_i \right)}{\partial x_k} =$	$= -\frac{\partial p}{\partial x_i} +$	$\frac{1}{Re}\frac{1}{\partial x}$	$\frac{\partial^2 u_i}{x_k \partial x_k} - \frac{\partial^2 u_i}{\partial x_k} = \frac{\partial^2 u_i}{\partial x_k} - $
Density	$\frac{\partial \rho}{\partial t} +$	$-\frac{\partial\left(u_k\rho\right)}{\partial x_k} =$	$\frac{1}{RePr}\frac{\partial x}{\partial x}$	$\frac{\partial^2 \rho}{\partial x_k}$	Mass
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$$Re = \frac{\sigma L}{\nu}, \qquad Fr = \frac{\sigma}{ND}$$

Visualization of flow past a sphere

Here we are looking at instantaneous transparent contours of the vorticity magnitude at Re=1,000 to visualize vortical structures in the wake.

The boundary layer shed off the sphere is laminar at the Reynolds number of interest. Unsteady vortex shedding at low frequency leads to a large scale spiral structure for the wake which persists for significant distance downstream. The separated boundary layer forms a thin shear layer which becomes unstable due to a Kelvin-Helmholtz type instability leading to small scale breakup of the spiral structure. Further downstream, the growth of instabilities leads to a transition from unsteady laminar flow near the sphere to turbulent flow in the intermediate wake.

Immersed boundary method

The immersed boundary method is a technique for simulating flow with complex geometry on a simple grid.

Basic idea:

- 1. Classify grid points as solid or fluid
- 2. Modify Navier-Stokes equations with forcing term to represent complex geometry boundary at locations not coincident with with gridpoints
- 3. Modify computational stencil around immersed body
- 4. Solve Navier-Stokes equations and equations for interpolation points simultaneously

Implementation:

Algorithm of Roman et. al., Computers & Fluids, 2009 Decouples fluid and solid nodes, sharp interface Designed for semi-implicit time advancement Single solution of momentum equations at each step Velocities in immersed boundary points are calculated by linear interpolation of intersection points on the body and projection points away from the body.





Outflow



Solid region

Data is only shown for $|\omega| \ge 0.25$. Red illustrates when $|\omega| \ge 4$, Blue illustrates when $|\omega| = 0.25$



Velocities at the intersection points are known from the no-slip boundary

Velocities at the projection points are calculated from a Taylor series expansion about the nearest fluid point.

> Immersed boundary point (IB) Intersection point (IP) **Projection point (PP)** Solid cell Nearest fluid neighbor to PP





Future work

Increasing the Reynolds number Incorporating the effect of density stratification Target values for thesis project: Re=10,000, Fr=4

Optimize numerical implementation

Target simulation requires O(1 billion grid points) and O(100,000) CPU hours

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